azbil

**Specification** 

# C7G Multi-loop Controller with Multifunction Display

### **Overview**

The C7G multi-loop controller with multifunction display (hereafter also called simply "this device") can calculate diagnostic parameters, known collectively as the health index, that help to predict failure of other equipment, in addition to calculations for PID (proportional, integral and derivative) control of process variables such as temperature, pressure, flow rate, pH, and liquid level.

The controller consists of a display unit with a 3.5-inch QVGA LCD and a touch panel, as well as a main unit capable of controlling up to four loops with an input sampling cycle of 10 ms and an indication accuracy of  $\pm 0.1$  %FS.

The display unit and main unit can be installed separately for installation flexibility.

A wide variety of interfaces, including Ethernet, RS-485 serial communication, microSD memory card, Micro USB port, and 7 digital input/outputs are provided as standard features. Setup, operation, and monitoring can be easily accomplished using the display unit and Smart Loader Package.

This controller is compliant with the IEC Directive and is CE marked.

### **Features**

- High-speed and high-accuracy control is available with an input sampling cycle as fast as 10 ms and an indication accuracy of  $\pm 0.1$  % FS. Process data can be stored with the compact data storage function (microSD card).
- Diagnostic and management information is created with our unique process data-processing technology (the health index function).
- One module can execute PID control for up to 4 loops.
- Various information is displayed on a 3.5-inch QVGA LCD with easy touchscreen operation.



- The display unit and main unit can be installed separately Standard distance: less than 30 m
- If display unit is separately powered: 30 to 100 m • Protective structure of display face: IP67
- Ethernet and RS-485 serial communications (Modbus) are
- supported as standard features.For setup and file management the SLP-C7 Smart Loader Package can be used.
- Parameters can be downloaded to the C7G when it is powered by the USB bus power function when the MicroUSB port and the PC are connected with a USB cable.

### **C7G Basic Functional Blocks**



# **Specifications**

Analog Input block		Input type	Full multi-range for thermocouple, resistance temperature detector (RTD), DC current, and DC voltage
		No. of control loops	4 loops max. (configurable by the loop type setting)
		Range type	Table 1, "Input types and ranges" (p. 8)
		Sampling cycle	10 ms, 50 ms, 100 ms (factory default; 50 ms)
		Burnout	Depends on the input range ( Table 1 "Input types and ranges " p. 8)
		Over-range judgment	Below -10 % or above 110 % of the range
		Decimal point position	0 to 4 digits after the decimal point are displayed. Values are displayed so that the entire
		Decimal point position	value does not exceed 5 digits (Note: Effective resolution depends on the range)
	Thermo-	Reference contact	+0.5 °C (ambient temperature 21 to 27 °C, under standard conditions)
	couple	compensation ac-	+1.5 °C (ambient temperature 0 to 50 °C, under standard conditions except for ambient
		curacy	temperature)
		Reference contact	Compensation within the C7G
		compensation method	
		Input bias current	0.12 µA max. (under standard conditions)
			*From the positive (+) terminal
		Allowable input voltage	-1.5 to +1.5 V
	Resistance	Measuring current	1.0 mA (typical, from terminals A and B, under standard conditions)
	tempera-	Allowable wiring	85 Ω max. (per wire)
	ture detec-	resistance	
	tor (RTD)	Effect of wiring resis-	0.013 °C/Ω
		tance	
	DC voltage	Input bias current	0 to 10 V range : 10 µA max. (under standard conditions)
	DC current		1–5 V or 0–5 V range: 5 µA max. (under standard conditions)
		Allowable input voltage	DC voltage input: -15 to +15 V
			DC current input: -1.5 to +1.5 V
		Input impedance	DC voltage input: 1 MΩ min.
			DC current input: 50 Ω
		Scaling	-32000 to +32000 U
			(Max. 5 digits within the above range, max. 4 digits after the decimal point, reverse scal-
			ing possible)
Display unit (inc	luded)	Screen specifications	3.5-inch QVGA LCD
(C7D-xxxxxx)		Status display (LED):	1 (power)
		Operation buttons	Touchscreen (resistive) and 3 hardware buttons
		Display power source	Main unit (if distance from connector on the main unit or connector on the additional
			display unit block to the display unit is less than 30 m)
			5 V DC external power supply (if distance from connector on the main unit or connector
		Drotaction rating	
			From the display time only (in the black)
		Service life of LCD	English/Japanese (switchable)
		Service life of LCD	light brightness)
DI (digital input)	1	No. of I/Os	7 max. (select DI, DO, or TP by setting), shared common
DO (digital outp	ut)		Note: TP (time proportioning output) can be selected for DI/DO terminals 4 to 7.
block	Digital input	Compatible output type	Non-voltage contacts or open collector (sink type)
		Open terminal voltage	7 V max.
		Terminal current	1 mA (under standard conditions)
		(when shorted):	
		On-state contact re-	$500 \Omega$ max. (under standard conditions)
		sistance (no-voitage	
		Off state contact ro	100 kO max (under standard conditions)
		sistanco (no-voltago	
		contact)	
		Allowable on-state	1 V max. (under standard conditions)
		residual current for	
		open collector	
		Allowable off-state	100 μA max. (under standard conditions)
		residual current for	
		open collector	
		Input sampling cycle	10 ms
		Minimum pulse width	20 ms min. (for 10 ms sampling cycle), 40 ms min. (50 or 100 ms sampling cycle)
		for ON detection	
		Function assignment	RUN/READY mode selection, AUTO/MANUAL mode selection, LSP/RSP mode selec-
			tion, SP group selection, CDS stop/start, etc.

DI (digital input)/	Digital output	Output method	Open collector (sink ty	pe)			
DO (digital output)		Load voltage	4.5 to 28.8 V DC				
block		Maximum load current	100 mA for each termin	nal			
		Overcurrent detection	130 mA or more				
			When an overcurrent is	s detected, the output is turned OFF, and the status is checked ev-			
			ery 5 seconds. If the status returns to normal, the output returns to normal automatically.				
		On-state residual voltage	0.5 V max. (under standard conditions)				
		Off-state leak current	100 µA max. (under sta	andard conditions)			
		Function assignment	Select an event status	or a standard bit code			
	Time pro-	Output method	Same as digital output				
	portional	Number of outputs	4 max. (DI/DO termina	ls 4 to 7)			
	output	Min. OFF time / ON time	In time proportional cy	cle shorter than 10 s: 1 ms			
			In time proportional cy	cle of 10 s or longer: 250 ms			
Control unit		Control operation	PID control (reverse action, direct action, heating and cooling action), ON/OFF control				
			(reverse action, direct	action)			
		PID Control	Proportional band (P)	0.1 to 3200 % (5 digits max. within this range, 4 digits max. after			
				the decimal point)			
			Integral time (I)	0 to 32000 s (5 digits max. within this range, 4 digits max. after			
				the decimal point)			
				No integral calculation when the setting is 0.			
			Derivative time (D)	0 to 32000 s (5 digits max. within this range, 4 digits max. after			
				the decimal point)			
				No derivative calculation when the setting is 0.			
			MV limits	-10 to +110 % (5 digits max. within this range, 4 digits max. after			
				the decimal point)			
			Manual reset -10 to +110% (5 digits max. within this range, 4 digits				
			the decimal point)				
			Number of PID groups         8 groups per loop				
			PID group selection SP group interlocking system				
			MV change limit 0 to 10000 %/s (5 digits max. within this range, 4 digits max.				
			after the decimal point)				
			No limit when the setting is 0.				
			Auto-tuning	PID automatic setting using the limit cycle method			
			Control cycle	Same as sampling cycle			
		SP	Number of LSP groups	8 groups per loop			
		(LSP: Local SP)	SP ramp unit	0: s, 1: min, 2: h			
			Ramp up and down	0 to 32000			
			slopes				
		Direct/reverse opera-	Switchable				
		tion selection					
		Heating/cooling con-	-100.0 to +100.0 %				
		troi deadband	22000 to 122000 (E d	isite may within this range. A disite may after the desired point)			
Analog input pro	beessing unit	and high limits	-32000 to +32000 (5 u	igits max. within this range, 4 digits max. after the decimal point)			
		Filtor	0 0000 to 120 00 s				
		Patio	0.0000 to 120.00 s				
		Riac	22000 to ±22000 (5 di	igite may within this range. A digite may after the desimal point			
Event functions		Operation type	-32000 t0 +32000 (3 til	mit DV high and low limits, doviation high limit, doviation low limit			
Event functions			deviation high and low	limits, deviation high limit (final SP basis), deviation low limit (final			
			SP reference) deviation	n high and low limits (final SP basis), SP high limit, SP low limit			
			SP high and low limits.	MV high limit, MV low limit, MV high and low limits, MFB high and			
			low limits, standard nui	merical code high limit, standard numerical code low limit, stan-			
			dard numerical code hi	igh and low limits, PV change rate, PV change rate high limit, PV			
			change rate low limit, s	standard numerical code change rate high limit, standard numerical			
			code change rate low I	imit, Alarm (state), READY (state), MANUAL (state), RSP (state),			
			AT running (state), SP	ramp running (state), control direct action (state), control with			
			estimated MFB (state),	timer (state)			
		Number of events	16				
		Main setting / subsetting	-32000 to +32000 (5 d	igits max. within this range, 4 digits max. after the decimal point)			
		Hysteresis	0 to 32000 (5 digits ma	ax. within this range, 4 digits max. after the decimal point)			
		READY mode operation	Selectable from "contin	nuation" and "forced OFF."			
		Direct/reverse	Select the polarity to tu	Irn ON/OFF in event output			
		Standby	0: None, 1: Standby, 2	: Standby + standby when the SP is modified			
		On-delay time	0 to 3200 s (4 digits ma	ax. within this range, 4 digits max. after the decimal point)			
		On-delay time 0 to 3200 s (4 digits max. within this range, 4 digits max. after the decimal poin					
		OFF-delay time		0 to 3200 s (4 digits max. within this range, 4 digits max. after the decimal point)			
Approximation b	y linearization	OFF-delay time Number of groups	0 to 3200 s (4 digits ma 8	ax. within this range, 4 digits max. after the decimal point)			
Approximation b	y linearization	OFF-delay time Number of groups Breakpoints per group	0 to 3200 s (4 digits ma 8 10	ax. within this range, 4 digits max. after the decimal point)			

Analog current Current		Type	4–20 mA DC / 0–20 mA DC
output block	output	Output type	Control output (MV) process value (PV) set value (SP) standard numerical code etc
	(1)	Δοςμιτοςγ	
	(-)	Allowable load racio	600 O may
		tanco	000 12 max.
		Output resolution	1/16000 min
	CT (current)	Decemberded our	1/16000 mm.
	CT (current)	recommended cur-	QN200A (noie dia. 5.8 mm, 800 lums), QN212A (noie dia. 12 mm, 800 lums)
	(1)		
	(1) Measuring current Maximum allowa		0.4–50.0 A AC, 50/60 HZ (peak current: 71 A, 800 turns, 1 power wire loop)
		Maximum allowable	70 AAC (peak current: 99 A max. with 800 turns and 1 pass of the power wire)
		current	
		Indication accuracy	±1 % FS ±1 digit (under standard conditions, CT accuracy is not included)
		Indication resolution	0.1 A AC
		Indication update cycle	100 ms
	VT (voltage)	Recommended volt-	81406725-003
	input	age transformer	Note: Not UL-certified.
	(1)	Voltage measurement	24 to 240 V AC, 50/60 Hz (peak voltage: 339 V max.; recommended voltage: transformer
		range	primary side 200 V, secondary side 10 V)
		Maximum allowable	264 V AC (peak voltage: 373 V; recommended voltage transformer primary side: 200 V,
		voltage	secondary side: 10 V)
		Indication accuracy	±1 % FS ±1 digit
		Indication resolution	0.1 V AC
		Input impedance	160 kΩ (typ)
		Indication update cycle	100 ms
Voltage pulse	Voltage	Output voltage	12 V DC +15/-10 % (under standard conditions)
output block	pulse output	Allowable current	25 mA max
	(1)	Load limit current	30 mA ±10 %
		OFF-state leak current	100 μA max. (under standard conditions)
		Output response time	100 µs max. for 10↔90 % of output voltage
CT (current)		Specifications	Same as CT (current) input for the analog current output block
	input		······································
	(2)		
Motor drive	Relay	Contact configuration	Switching between OPEN output and CLOSE output (with function for turning both
output block	output		outputs OFF at the same time)
	OPEN	Contact rating	250 V AC, 2 A (cos φ = 0.4); 24 V DC, 2.5 A (L/R = 0.7 ms)
	CLOSE	Contact voltage	250 V AC / 125 V DC max.
		Service life	100,000 cycles min. (at the rated specifications)
		Minimum require-	24 V DC, 40 mA
		ments for switching	
		Interlock	With prevention of simultaneous ON if contact welding occurs
	Motor feed-	Allowed potentiom-	100 to 2500 $\Omega$ (wiring resistance included)
	back (MFB)	eter resistance	
	input	Indication accuracy	±0.5 % FS (under standard conditions)
	1	Sampling cycle	100 ms
		Operation at burnout	Y line break: downscale Other line break: upscale
Clock block	1	Clock function	Hours, minutes, seconds, calendar (vears 2000 to 2099, supports leap vears)
(with battery)		Clock accuracy	Monthly error: ±65 s (under standard conditions)
		Service life	10 years (battery life when not energized under standard conditions)
		Built-in battery	Lithium battery
		Block replacement	Possible (ontional parts sold separately)
Additional displa	av unit block	Number of connect-	
	ay and block	able units	'
		Connector	R.I-45
External com-	Ethernet	Transmission line tune	Compliant with IEEE 802 3u 100BASE-TX (EastEthernet)
munication	Luieniet	Communication mothed	
		No. of connections	3 (for Modbue/TCD and loader communication via Ethornet)
		Transmission and the	
		Transmission speed	
		No. of physical ports	(KJ-40)
		(connectors)	
		Destausly	UTE CADIE (4F) CAL DE ITIITI. (SITAIGNT) (ANSI/TIA/EIA-508-B DOTH ENDS)
		Protocol:	NIODDUS/ I CP, MITSUDISNI SLMP (3E) (TOT PLC link communication)

External com-	RS-485	Signal level	RS-485-compliant
munication	communi-	Network	Multidrop (up to 31 slave stations for 1 host station)
	cation	Communications/syn-	Half-duplex, start-stop synchronization
		chronization type	
		Maximum cable length	500 m
		No. of communication wires	3-wire system
		Transmission speed	9600, 19200, 38400, 57600, 115200 bps
		Terminating resistor	External (120 Ω, 1/2 W min.)
		Data length	8 bits
		Stop bits	1 or 2 bits
		Parity bit	Even parity, odd parity, or no parity
		Protocol	Modbus/RTU
	Loader	Dedicated PC loader	SI P-C7E.I91 (free version) SI P-C7-J91 (paid version)
	communi-	Cable	USB-to-Micro-USB (Type A/B) cable (USB 2.0 supported .5 m max.) or Ethernet cable
	cation	Power supply	When connected with a LISB cable, the device can be powered by the PC and param-
		r onor ouppry	eters can be changed
Data storage		SD	microSD/SDHC-compliant (4 GB) for the compact data storage and health index functions
General specific	ations	Backup memory	EEPROM (durability: 1 million erase-write cycles may, for parameter settings)
General Specific	ations	Bower consumption	AC models: 25 VA 10 W may DC models: 12 W may
		Power consumption	25 A max /10 ms max
		Start dolay at nowar on	10 c max. (the time until permal operation begins under standard conditions)
		Allowable transient	AC modelo: 20 mo min. DC modelo: 5 mo min.
		power loss	
		Insulation resistance	20 MΩ min. (between power supply terminal (#1 or #2) and frame ground terminal (#3), with a 500 V DC megger)
		Dielectric strength	<ul> <li>AC models:</li> <li>1500 V AC for 1 min Between AC power supply terminal (#1 or #2) and frame ground terminal (#3) Between AC power supply terminal (#1 or #2) and secondary terminals (except for motor block output terminals (#1 to #3)) Between AC power supply terminal (#1 or #2) and motor block terminals (#1 to #3) Between motor block output terminals (#1 to #3) and frame ground terminal (#3) Between motor block output terminals (#1 to #3) and secondary terminals other than motor block output terminals (#1 to #3)</li> <li>DC models</li> <li>1500 V AC for 1 min Between motor block output terminals (#1 to #3) and frame ground terminal (#3) Between motor block output terminals (#1 to #3) and DC power supply terminal (#1 or #2) Between motor block output terminals (#1 to #3) and secondary terminals other than motor block output terminals (#1 to #3) and secondary terminals other than motor block output terminals (#1 to #3) Between DC power supply terminal (#1 or #2) and frame ground terminal (#3) Between DC power supply terminal (#1 or #2) and frame ground terminal (#3) Between DC power supply terminal (#1 or #2) and frame ground terminal (#3) Between DC power supply terminal (#1 or #2) and secondary terminals other than motor block output terminals (#1 to #3)</li> </ul>
		Case material	Main unit: Modified PPE (case), polycarbonate (board holder, front mask) Display unit: Modified PPE (case), polycarbonate (back cover), PET film (protective sheet)
		Applicable standard	DidUK
			Note: During EMC testing, the reading or output may fluctuate by the equivalent of ±10 % FS. cULus: UL 61010-1, CSA C22.2 No. 61010-1 (applicable model needs to be selected)
		Overvoltage category	Category II (IEC 60364-4-443, IEC 60664-1)
		Installation	Main unit: Mounting on a DIN rail (standard) or on the display unit using the mounting
			bracket Display unit: Mounting using $\varphi$ 3 screws (standard) or the mounting bracket (mount in a 92 × 92 mm hole)
		Weight	Main unit: 500 g max. Display unit: 150 g max. Integrated mounting bracket : 150 g max.
		Built-in clock accuracy	<ul> <li>Monthly error: ±140 s (±65 s if the clock block with battery is used)</li> <li>Note: The time is reset to 00:00:00 1/1/2000 (default) at power-on (including power restoration).</li> <li>Note: For a firmware version of the MAIN block 3.*.* or earlier (* represents any number), the time is reset to 00:00:00 1/1/2014 (default).</li> </ul>

General speci-	Standard	Ambient temperature	23 °C	-2/+5 °C			
fications	conditions	Ambient humidity	60 ±5	% RH			
		Power voltage	AC m	odels: 105 V AC ±10 %. DC models: 24 V DC ±5 %			
		Power frequency	AC m	odels: 50 Hz ±1 %, 60 Hz ±1 %			
		Vibration	0 m/s	2			
		Shock	0 m/s	2			
		Mounting angle	Main	unit: Reference plane ±3 °, Display unit: No restriction (	if mounted separately from		
			the m	ain unit)			
		Space	Refer	ence plane ±10 $^\circ$ (main unit, and main unit and display $\iota$	unit in integrated mounting),		
			no res	striction for display unit in standard mounting			
	Operating	Ambient temperature	0 to 5	0 °C (0 to 40 °C if 2 or more main units are gang-mounte	ed), 0 to 50 °C (display unit)		
	conditions	Ambient humidity	10 to	90 % RH (without condensation)			
		Rated power	AC m	odels: 100 to 240 V AC (operating input voltage: 85 to 2	64 V AC)		
			DC m	odels: 24 V DC (operating input voltage: 20.4 to 28.8 V	DC)		
		Power frequency	AC models: 50 Hz ±2 % or 60 Hz ±2 %				
		Vibration	0 to 5 m/s <sup>2</sup> (10 to 60 Hz for 2 h each in x, y, and z directions)				
		Shock					
		Mounting angle	Reference plane ±10 ° (main unit, and main unit and display unit in integrated mounting				
		Altitude		m may			
		Altitude	2000	m max.			
		Pollution degree	2				
		Installation location	1000	rs			
		Space	50 mr	n min. above and below			
	Trancporta	Ambient temperature					
	tion and	Ambient temperature	-20 to	95 % PH (without condensation)			
	storage	Vibration	0 to 1	$0 \text{ m/s}^2$ (10 to 60 Hz for 2 h each in x, y, and z directions)	١		
	conditions	Shock	0 to 3	$00 \text{ m/s}^2$ (10 to 00 Hz for 2 frequential, y, and 2 directions)	/		
Accessories		ltem	Otv				
1000000100	Standard gast	(et	1	For the display unit of the standard model (C7G 4)			
	Display unit m	ounting screws (6 mm)	5	Standard model (C7G 4)			
	Display unit mounting screws (0 mm)		5	Standard model (C7G 4)			
	Set screws (fo	or securing temporarily)	2	Standard model (C7G 4)			
	Gasket with 9	2 × 92 mm hole	1	Integrated mounting model (C7G 3)			
	Integrated-mo	unting bracket	1	Integrated mounting model (C7G 3)			
	Display unit m	ounting screws (6 mm)	5	Integrated mounting model (C7G 3)			
	Integrated-mo	unting cable	1	Integrated mounting model (C7G 3)			

#### Table 1. Input types and ranges

Input type	Range	Sensor		Ra	nge	Accuracy	Resolution	Burnout
	type Nos.							
Thermocouple	1	K	-200	to	+1200 °C	±0.1 % FS ± 1 digit *1	0.1 °C	Upscale
	2	К	0	to	1200 °C	±0.1 % FS ± 1 digit	0.1 °C	(110 % FS)
	3	K	0	to	800 °C	±0.1 % FS ± 1 digit	0.1 °C	
	4	K	0	to	600 °C	±0.1 % FS ± 1 digit	0.1 °C	
	5	K	0	to	400 °C	±0.1 % FS ± 1 digit	0.1 °C	
	6	K	-200	to	+400 °C	±0.1 % FS ± 1 digit *1	0.1 °C	
	7	K	-200	to	+200 °C	±0.1 % FS ± 1 digit *1	0.1 °C	
	8	J	0	to	1200 °C	±0.1 % FS ± 1 digit	0.1 °C	
	9	J	0	to	800 °C	±0.1 % FS ± 1 digit	0.1 °C	
	10	J	0	to	600 °C	±0.1 % FS ± 1 digit	0.1 °C	
	11	J	-200	to	+400 °C	±0.1 % FS ± 1 digit *1	0.1 °C	
	12	E	0	to	800 °C	±0.1 % FS ± 1 digit	0.1 °C	
	13	E	0	to	600 °C	±0.1 % FS ± 1 digit	0.1 °C	
	14	Т	-200	to	+400 °C	±0.1 % FS ± 1 digit *1	0.1 °C	
	15	R	0	to	1600 °C	±0.1 % FS ± 1 digit *2	0.1 °C	
	16	S	0	to	1600 °C	±0.1 % FS ± 1 digit *2	0.1 °C	
	17	В	0	to	1800 °C	±0.2 % FS ± 1 digit *3	0.1 °C	
	20	WRe5-26	0	to	1400 °C	±0.1 % FS ± 1 digit	0.1 °C	
	21	WRe5-26	0	to	2300 °C	±0.1 % FS ± 1 digit	0.1 °C	

\*1. For -200 to 0 °C,  $\pm 0.2$  % FS  $\pm 1$  digit

\*2. For 0 to 100 °C, ±0.2 % FS ±1 digit

\*3. For 0 to 260 °C, ±4 % FS ±1 digit. For 260 to 800 °C, ±0.4 % FS ±1 digit

Input type	Range type Nos.	Sensor		Rar	ige	Accuracy	Resolution	Burnout
Resistance	41	Pt100	-200	to	+500 °C	±0.1 % FS ± 1 digit	0.1 °C	Upscale
temperature	43	Pt100	-200	to	+200 °C	±0.1 % FS ± 1 digit	0.01 °C	(110 % FS)
detector	45	Pt100	-100	to	+300 °C	±0.1 % FS ± 1 digit	0.01 °C	
(RID)	47	Pt100	-100	to	+200 °C	±0.1 % FS ± 1 digit	0.01 °C	
	49	Pt100	-100	to	+150 °C	±0.1 % FS ± 1 digit	0.01 °C	
	51	Pt100	-50	to	+200 °C	±0.1 % FS ± 1 digit	0.01 °C	
	53	Pt100	-50	to	+100 °C	±0.1 % FS ± 1 digit	0.01 °C	
	55	Pt100	-60	to	+40 °C	±0.1 % FS ± 1 digit	0.01 °C	
	57	Pt100	-40	to	+60 °C	±0.1 % FS ± 1 digit	0.01 °C	
	59	Pt100	-10	to	+60 °C	±0.1 % FS ± 1 digit	0.01 °C	
	61	Pt100	0	to	100 °C	±0.1 % FS ± 1 digit	0.01 °C	
	63	Pt100	0	to	200 °C	±0.1 % FS ± 1 digit	0.01 °C	
	65	Pt100	0	to	300 °C	±0.1 % FS ± 1 digit	0.01 °C	
	67	Pt100	0	to	500 °C	±0.1 % FS ± 1 digit	0.1 °C	
Linear	86	Voltage (V)	1	to	5 V	±0.1 % FS ± 1 digit	1/90000 or better	Downscale (-10 % FS)
	87	Voltage (V)	0	to	5 V	±0.1 % FS ± 1 digit		Burnout not detected (around 0 % FS)
	88	Voltage (V)	0	to	10 V	±0.1 % FS ± 1 digit		Burnout not detected (around 0 % FS)
	89	Current (mA)	0	to	20 mA	±0.1 % FS ± 1 digit		Burnout not detected (around 0 % FS)
	90	Current (mA)	4	to	20 mA	±0.1 % FS ± 1 digit		Downscale (-10 % FS)

Input type	Range type Nos.	Sensor	Range	Accuracy	Resolution	Burnout
Not used	0	None	Always 0			-

#### Input sensor standards reference

ThermocoupleK, E, J, T, B, R, S:JIS C 1602-2015WRe5-26:ASTM E988-96 (Reapproved 2002)(JIS C 1602:2015, C thermocouple)Resistance temperature detectorPt100: JIS C 1604-2013

#### Table 2. Compact data storage (CDS) and health index settings

Item		Specifications	Note
Compact data stars as		Specifications	Note
			Set according to the response time of the control
(CD3)	2.1	•	laigei
	3.10	) s	
	4:1	min	
	5: 10	) min	
Operation ty	/pe 0: St	00	Operates when ON and records data.
	1: D	1 status	
	2: D	2 status	
	11 to	26: Events 1 to 16	
	1024	to 2047: Standard bit codes	
Health Index Operation ty	/pe 0: St	ор	Operates for loops 1 to 4 individually
	1: D	1 status	
	2: D	2 status	
	11 to	26: Events 1 to 16	
Durkesse	1024	to 2047. Standard bit codes	
R value sca		10	Result of primary operation × power of 10
	0.00		
Deviation lo	w limit 0.00	00 to 32000	No low limit when 0.0000
Deviation hi	gh limit 0.00	00 to 32000	No high limit when 0.0000
SP high limi	t -320	00 to +32000	
File Saved to	Micr	oSD memory card	
Saving timir	ng Ever	y 8 KB	
Saved form:	at Text	(CSV)	Extension: .DAT
Number of f	iles saved 6500	00 max.	
Records Context sec	tion P (P	roportional band)	Setting at CDS start
(for Data selection = Stan-	I (Int	egral time)	
dard)	D (D	erivative time)	
	OL		
	OH		
	SPI	mit	
	Defi	nite R value	Definite value at CDS end
Chronologic	al data Time	estamp	
selection (c	clic SP		
recording	PV		
	MV		
	R va	lue	
	DMS		CT input*
			VT input*
	Actu	ator (hoator) resistance	Calculates using the CT input current and the VT
	Actu		input voltage)
Records Number of (	tata items 1 to	40	
(for Data selection = Data type		to 2047: Standard bit codes	The number of items set in "Number of data
Custom) (Data 1 to 4	0) 2048	to 3071: Standard numeri-	items" is enabled
	cal c	odes	
	Ø	Table 3, "Standard bit codes"	
	(p. 1	0),	
		Table 4, "Standard numerical	
	code	es" (p. 11).	
Recording	Data	is recorded periodically ac-	
	cord	ing to the settings for "Data	
Diamantia mananta di di di di	type	and inumber of data items."	
Uiagnostic parameter   Health index	k Defi	nite R value	In the normalization responsiveness (Kp/Tp)
			time constant on Th
Calculation	timina Whe	n the health index function	Calculated from the data when the PV is rising

\* The recorded details vary depending on the type of output block to which the MV is assigned. AO-C block: RMS current, RMS voltage, actuator resistance V-P block: CT1 RMS current, CT2 RMS current

#### Table 3. Standard bit codes

The range of standard bit codes is 1024 to 2027.

Codes not listed below are reserved for the system, so do not use them for configuration

Standard bit code	Meaning of the standard bit codes
1024	Always 0 (Off)
1024	Always 1 (On)
1023	Always I (OII)
1000	
1089	Event 2
1090	Event 3
1091	Event 4
1092	Event 5
1093	Event 6
1094	Event 7
1095	Event 8
1096	Event 9
1000	Event 10
1007	Event 10
1090	Event 40
1099	Event 12
1100	Event 13
1101	Event 14
1102	Event 15
1103	Event 16
1120	CT1 heater burnout detection
1121	CT2 heater burnout detection
	(block A2)
1122	CT1 heater burnout detection
	(block B2)
1123	CT2 heater burnout detection
1104	CT1 hostor humant data that
1124	
1125	C12 heater burnout detection
410-	
1126	CI1 heater burnout detection
	(block B1)
1127	CT2 heater burnout detection
	(block B1)
1128	CT1 overcurrent detection (block
	A2)
1129	CT2 overcurrent detection (block
	A2)
1130	CT1 overcurrent detection (block
	B2)
1131	CT2 overcurrent detection (block
	B2)
1132	CT1 overcurrent detection (block
	A1)
1133	CT2 overcurrent detection (block
	A1)
1134	CT1 overcurrent detection (block
110-1	B1)
1125	CT2 overcurrent dotaction (block
1100	
4100	
1136	CI1 short-circuit detection (block
	A2)
1137	CT2 short-circuit detection (block
	A2)
1138	CT1 short-circuit detection (block
	B2)
1139	CT2 short-circuit detection (block
	B2)
1140	CT1 short-circuit detection (block
	A1)
1141	CT2 short-circuit detection (block
	A1)
1142	CT1 short-circuit detection (block
1174	B1)
1143	CT2 short-circuit detection (block
175	B1)
1160	DI/DO1 terminal status
1 1100	וסייסטי ובווווומו פומנעפ

Standard	Meaning of the standard bit codes
1109	DI/DO2 terminal status
1170	DI/DO3 terminal status
11/1	DI/DO4 terminal status
1172	DI/DO5 terminal status
1173	DI/DO6 terminal status
1174	DI/DO7 terminal status
1280	V-P terminal status (block A2)
1281	V-P terminal status (block B2)
1282	V-P terminal status (block A1)
1283	V-P terminal status (block B1)
1408	User-defined bit 1
1409	User-defined bit 2
1410	User-defined bit 3
1411	User-defined bit 4
1412	User-defined bit 5
1413	User-defined bit 6
1414	User-defined bit 7
1415	User-defined bit 8
1416	User-defined bit 9
1417	User-defined bit 10
1418	User-defined bit 11
1419	User-defined bit 12
1420	User-defined bit 13
1421	User-defined bit 14
1422	User-defined bit 15
1423	User-defined bit 16
1440	Result of logical operation 1
1441	Result of logical operation 2
1442	Result of logical operation 3
1443	Result of logical operation 4
1444	Result of logical operation 5
1445	Result of logical operation 6
1446	Result of logical operation 7
1447	Result of logical operation 8
1448	Result of logical operation 9
1449	Result of logical operation 10
1450	Result of logical operation 11
1451	Result of logical operation 12
1452	Result of logical operation 13
1453	Result of logical operation 14
1454	Result of logical operation 15
1455	Result of logical operation 16
1504	At CDS start
1505	Loop 1 health index running
1506	Loop 2 health index running
1507	Loop 3 health index running
1508	Loop 4 health index running
1517	Display unit connection status
1518	Additional display unit connection
4=0-	status
1568	LOOP 1 RUN/READY status
1569	LOOP 2 RUN/READY status
1570	LOOP 3 RUN/READY status
1571	LOOP 4 RUN/READY status
1584	Loop 1 Auto/manual status
1585	Loop 2 Auto/manual status
1586	Loop 3 Auto/Manual status
1587	Loop 4 Auto/Manual status
1600	Loop 1 AT stop/start status
1601	Loop 2 AT stop/start status
1602	Loop 3 AT stop/start status
1603	Loop 4 AT stop/start status
1616	Loop 1 LSP/RSP status
1617	Loop 2 LSP/RSP status
1648	Loop 1 SP ramp-up in progress
1649	Loop 2 SP ramp-up in progress

Standard	
bit code	Meaning of the standard bit codes
1650	Loop 3 SP ramp-up in progress
1651	Loop 4 SP ramp-up in progress
1652	Loop 1 SP ramp-down in progress
1653	Loop 2 SP ramp-down in progress
1654	Loop 3 SP ramp-down in progress
1655	Loop 4 SP ramp-down in progress
1792	All typical alarms (logical OR of
	all alarms be displayed)
1824	Loop 1 PV low limit error
1825	Loop 1 PV high limit error
1826	Loop 1 RSP low limit error
1827	Loop 1 RSP high limit error
1828	Loop 2 PV low limit error
1829	Loop 2 PV high limit error
1830	Loop 2 RSP low limit error
1831	Loop 2 RSP high limit error
1832	Loop 3 PV low limit error
1833	Loop 3 PV high limit error
1836	Loop 4 PV low limit error
1837	Loop 4 PV high limit error
1880	MFB input error
1884	Adjusting MFB
1888	Estimating MFB
1896	MFB adjustment error
1900	Motor drive output OPEN
1904	Motor drive output CLOSE
1920	Reception monitoring 1
1921	Reception monitoring 2
1922	CTA/T input error (block A2 CT)
1952	CT//T input error (block A2 CT)
1953	CT/VT input error (block B2 CT)
1954	CT//T input error (block B2 VT)
1956	CT/VT input error (block A1 CT)
1957	CT/VT input error (block A1 VT)
1958	CT/VT input error (block B1 CT)
1959	CT/VT input error (block B1 VT)
1960	CT/CT input error (block A2 CT1)
1961	CT/CT input error (block A2 CT2)
1962	CT/CT input error (block B2 CT1)
1963	CT/CT input error (block B2 CT2)
1964	CT/CT input error (block A1 CT1)
1965	CT/CT input error (block A1 CT2)
1966	CT/CT input error (block B1 CT1)
1967	CT/CT input error (block B1 CT2)
1973	Memory error
1977	Battery error (CLOCK block)
1991	Block error
1992	SD card error
2000	Block alarm IO failure (block A1)
2001	Block alarm IO failure (block A2)
2002	Block alarm IO failure (block A3)
2003	Block alarm IO failure (block A4)
2004	Block alarm IO failure (block B1)
2005	Block alarm IO failure (block B2)
2006	BIOCK alarm IO failure (block B3)
2007	Block alarm IO failure (block B4)
2008	BIOCK alarm HMI block failure
2009	BIOCK AIARM SUB2 DIOCK TAILURE
2010	(NJ-403) Block alarm SLIP1 block foilure
2010	
2011	Block alarm MAIN block failure
2011	

#### Table 4. Standard numerical codes

The range of the standard numerical codes is 2048 to 2790.

Codes not listed below are reserved for the system, so do not use them for configuration.

Standard	Meaning of the standard
numeri-	numerical codes
	Alwaya 0.0
2040	Always 0.0
2111	User-defined value 1
2112	User-defined value 2
2113	User-defined value 3
2114	User-defined value 4
2115	User-defined value 5
2110	User-defined value 6
2117	
2110	User-defined value o
2119	User defined value 9
2120	User-defined value 10
2121	User-defined value 12
2122	User-defined value 13
2123	User-defined value 14
2124	Liser-defined value 15
2125	User-defined value 16
2304	AI (block A4)
2305	AI (block B4)
2306	AI (block A3)
2307	AI (block B3)
2312	PV (block A4)
2313	PV (block B4)
2314	PV (block A3)
2315	PV (block B3)
2320	Loop 1 PV
2321	Loop 2 PV
2322	Loop 3 PV
2323	Loop 4 PV
2336	Loop 1 SP (in use)
2337	Loop 2 SP (in use)
2338	Loop 3 SP (in use)
2339	Loop 4 SP (in use)
2352	Loop 1 SP (final value)
2353	Loop 2 SP (final value)
2354	Loop 3 SP (final value)
2300	
2410	
2418	Loop 3 MV
2419	Loop 4 MV
2432	Loop 1 MV for heating
2433	Loop 2 MV for heating
2434	Loop 3 MV for heating
2435	Loop 4 MV for heating
2448	Loop 1 MV for cooling
2449	Loop 2 MV for cooling
2450	Loop 3 MV for cooling
2451	Loop 4 MV for cooling
2464	MFB opening amount (estimated)
2472	MFB opening amount (actual value)
2479	MFB count value
2496	CT1 measured current when output ON (block A2)
2497	CT2 measured current when output ON (block A2)
2498	CT1 measured current when
	output ON (block B2)

Standard	Meaning of the standard
numeri-	numerical codes
cal codes	
2499	output ON (block B2)
2500	CT1 measured current when
	output ON (block A1)
2501	CT2 measured current when
	output ON (block A1)
2502	CT1 measured current when
2503	CT2 measured current when
2505	output ON (block B1)
2512	CT1 measured current when
	output OFF (block A2)
2513	CT2 measured current when
	output OFF (block A2)
2514	CT1 measured current when
	output OFF (block B2)
2515	C12 measured current when output OEE (block B2)
2516	CT1 measured current when
2010	output OFF (block A1)
2517	CT2 measured current when
	output OFF (block A1)
2518	CT1 measured current when
	output OFF (block B1)
2519	CT2 measured current when
2528	Loop 1 doviation (P)(_SP)
2520	Loop 2 deviation (PV - SP)
2520	Loop 2 deviation ( $PV = SP$ )
2531	1  oop 4 deviation (PV - SP)
2544	CT input value (block A2)
2545	CT input value (block B2)
2546	CT input value (block A1)
2547	CT input value (block B1)
2548	VT input value (block A2)
2549	VT input value (block B2)
2550	VT input value (block A1)
2551	VT input value (block B1)
2552	Resistance (block A2)
2553	Resistance (block B2)
2554	Resistance (block A1)
2555	Resistance (block B1)
2656	Event 1 timer remaining time
2657	Event 2 timer remaining time
2658	Event 3 timer remaining time
2659	Event 4 timer remaining time
2660	Event 5 timer remaining time
2661	Event 6 timer remaining time
2662	Event / timer remaining time
2663	Event 8 timer remaining time
2664	Event 9 timer remaining time
2005	Event 10 timer remaining time
2000	Event 12 timer remaining time
2668	Event 13 timer remaining time
2660	Event 14 timer remaining time
2670	Event 15 timer remaining time
2671	Event 16 timer remaining time
2736	CT1 Time proportioning current
	(block A2)
2737	CT2 Time proportioning current
	(block A2)

Standard numeri- cal codes	Meaning of the standard numerical codes
2738	CT1 Time proportioning current (block B2)
2739	CT2 Time proportioning current (block B2)
2740	CT1 Time proportioning current (block A1)
2741	CT2 Time proportioning current (block A1)
2742	CT1 Time proportioning current (block B1)
2743	CT2 Time proportioning current (block B1)
2752	Loop 1 definite R value
2753	Loop 2 definite R value
2754	Loop 3 definite R value
2755	Loop 4 definite R value
2760	Loop 1 R value
2761	Loop 2 R value
2762	Loop 3 R value
2763	Loop 4 R value
2768	AO-C percent output value (block A2)
2769	AO-C percent output value (block B2)
2770	AO-C percent output value (block A1)
2771	AO-C percent output value (block B1)
2776	V-P percent output value (block A2)
2777	V-P percent output value (block B2)
2778	V-P percent output value (block A1)
2779	V-P percent output value (block B1)
2787	TP percent output value (DO4)
2788	TP percent output value (DO5)
2789	TP percent output value (DO6)
2790	TP percent output value (DO7)

## **Model selection**

#### Example: C7GA411CC0D00

	Main unit			I/O slot				Other								
Ba	sic mo	del N	lo.	Comm.	Size	Slots A3, A4	Slots B3, B4	Slots A1, A2	Slots B1, B2	Option	Add'l proc.	Add'l spec.	Special support	Description		
1	2		3	4	5	6	7	8	9	10	11	12	13			
С	7		G											Multi-loop controller with multifunction display		
	A											Communication (Ethernet, RS-485, USB), DI/DO (× 7)				
					3									Integrated-mounting kit included *1		
					4									Standard mounting	Slot A2	Slot A4
						1								PV/1 (full-multi) x 1	SIULAS	510LA4
						2								PV1 (full-multi) + PSP1 (full-multi) *2	Δ1	
						-									Slot B3	Slot B4
							0		<u> </u>					None	CIOC DO	OIOT D4
Condit	ion:						1							PV2 (full-multi) × 1		AI
Selecta	ble if th	e 6th	diait of	the mode	Inumber											
(slots A	3, A4) i	s "2."					2							PV2 (full-multi) + RSP2 (full-multi) *3	AI	AI
										r				T	Slot A1	Slot A2
								С						Current output (CT and VT inputs, 1 each) × 1		AO-C
								V						Voltage pulse output (2 CT inputs) × 1		V-P
								F						Current output (CT and VT inputs, 1 each) × 2	AO-C	AO-C
								w						Voltage pulse output (2 CT inputs) × 2	V-P	V-P
					N						Current output (CT and VT inputs, 1 each) + voltage pulse output (2 CT inputs)	V-P	AO-C			
Condition:												Slot B1	Slot B2			
Selectable if the 8th digit of the model number (slots A1, A2) $\dots$ is V, C, or F					0					None						
Selectable if the 8th digit of the model number (slots A1, A2) $\dots$ is C, F, or N					с					Current output (CT and VT inputs, 1 each) × 1		AO-C				
Selectable if the 8th digit of the model number (slots A1, A2) is V. C. W. or N					v					Voltage pulse output (2 CT inputs) × 1		V-P				
Selecta A2) is F	ble if th	ne 8tł	h digit o	of the mod	el numbe	r (slots A	A1,		F					Current output (CT and VT inputs, 1 each) × 2	AO-C	AO-C
Selecta A2) is V	ble if ti V or N	ne 8tł	h digit o	of the mod	el numbe	r (slots A	A1,		w					Voltage pulse output (2 CT inputs) × 2	V-P	V-P
Selecta A2) is F	ble if th or N.	ne 8tł	h digit o	of the mod	el numbe	r (slots A	A1,		N					Current output (CT and VT inputs, 1 each) + voltage pulse output (2 CT inputs)	V-P	AO-C
Selecta is C, F,	ble if tł or N.	ne 8tł	h digit o	of the mod	el numbe	r (slots A	A1, A2)		G					Current output (CT and VT inputs, 1 each) + additional display unit	HMI2	AO-C
Selectable if the 8th digit of the model number (slots A1, A2) is V. C. W. or N.				н					Voltage pulse output (2 CT inputs) + additional display unit	HMI2	V-P					
Selectable if the 8th digit of the model number (slots A1, A2) is C, F, or N.				L					Current output (CT and VT inputs, 1 each) + clock (with battery)	Clock	AO-C					
Selectable if the 8th digit of the model number (slots A1, A2) is V, C, W, or N.					Р					Voltage pulse output (2 CT inputs) + clock (with battery)	Clock	V-P				
										0				None		
											0			None		
											D			With inspection report		
											Y			With traceability certificate		
Condit	ion:											0		AC power. CE, KC, GB-compliant		
Selecta (slots E	ble if th 1, B2)	ne 8th is 0,	n digit of C, or F.	f the mod	el numbei	r (slots A	.1, A2) is	C or F a	and the 9	9th digit		А		AC power. CE, KC, GB, UL-compliant		
												D		DC power. CE, KC, GB-compliant		
													0	No special support		
* 4 *			atta - I	ا اممد		ا م الم م						law		Provide the second s		
п. А	rear-r	nou	nrina t	Dracket	and a d	redicat	ea	S	vmpo		SIOCK N	vame		Description		

#### A rear-mounting bracket and a dedicated cable for connecting the display unit are included with the product.

- \*2. RSP1 can be switched for use as PV3.
- \*3. RSP2 can be switched for use as PV4.
- \*4. Current transformer (CT) and voltage transformer (VT) are not included.
- \*5. Additional display unit is not included.

#### Full-multi range (thermocouple, RTD, DC current, DC voltage) input × 1 AI Analog Input V-P Voltage pulse output (12 V DC) × 1 Voltage pulse Two input terminals for the current transformer (CT) for detecting heater output burnout, overcurrent, and short circuit are included.\*4 Current output (4-20 mA DC / 0-20 mA DC) × 1 AO-C Analog current Input terminals for the current transformer (CT) for measuring current and output the voltage transformer (VT) for measuring voltage are included (1 each).\*4 HMI2 Additional display Connector for the second display unit \*5 unit Clock Clock function Clock (available for CDS and health index) with a battery

#### Model No. recommendations

			Current outp	ut			
Digits 8 & 9	If 1 output: CO	⇒	If 2 outputs: CC	⇒	If 3 outputs: FC	-	If 4 outputs: FF
	A     B       1     1       AO-C     2		A B 1 AO-C AO-C 2		A         B           A0-C         1           A0-C         2		A         B           Aoc         Aoc           Aoc         Aoc           Aoc         Aoc           2
			Analog inpu	ıt			
Digits 6 & 7	If 1 input: 10	-	If 2 inputs: 11	⇒	If 3 inputs: 21	-	If 4 inputs: 22
	A B 3 AI 4		A B 3 AI AI 4		A B AI 3 AI AI 4		A B AI AI 3 AI AI 4

# • Sample block implementations for model No. and slot positions



# Model selection (models with motor output)

Image: model         No.         Size         A4         Ba         A2-3, B2-3         A1, B1         Option         Addr. proc. proc. proc. proc.         Addr. proc. proc. proc.         Support         Description           1         2         3         4         6         7         8         9         10         1         12         13           C         7         6         6         7         8         9         10         1         12         13           C         7         6         6         7         8         9         10         1         12         13           3         10         1         1         1         1         1         1         1         1         1         1         1         10         1         1         1         1         1		Example: C7GA410M00						10000										
Basic model No.         Comm.         Size         A         B         B2-3, B2-3, a, 1, B1         AddIt B2-3, basic         AddIt B2-3, basic         AddIt B2-3, basic         AddIt B2-3, basic         AddIt B2-3, B2-3, basic         AddIt B2-3, B2			М	ain uni	t			I/O	slot			Ot	her					
1       2       3       4       5       6       7       8       9       10       11       12       13       Multi-loop controller with multifunction display         C       7       6       A       Image: Control of the second	Ba	sic mo	del N	lo.	Comm.	Size	A4	B4	A2–3, B2–3	A1, B1	Option	Add'l proc.	Add'l spec.	Specia suppo	Description			
C       7       G       A       Image: Communication (Septex)         A       Image: Communication (Septex)       Sect A4         3       Image: Communication (Septex)       Sect A4         4       Image: Communication (Septex)       Sect A4         4       Image: Communication (Sect A4)       Sect A4         1       Image: Communication (Sect A4)       A         1       Image: Communicatimanet (Communicatimanet (Communicatimanet (Co	1	2		3	4	5	6	7	8	9	10	11	12	13				
3 Commutation (Ethemet, RS-485, USB), DUDO (×7)   4 0   4 0   4 0   1 1    1 1   1	С	7		G											Multi-loop controller with multifunction display			
<ul> <li>integrated-mounting included "</li> <li>integrated-mounting</li> <li>integrate</li></ul>	A									Communication (Ethernet, RS-485, USB), DI/DO (× 7)								
4       Image: Contrast of the current output (CT and VT inputs, 1 each) × 1       AI         9       Sample block implementations for model No. and slot positions       0       Image: Contrast output (CT and VT inputs, 1 each) × 1       AO-C         9       Image: Contrast output (CT and VT inputs, 1 each) × 1       AO-C       V-P         9       Image: Contrast output (CT and VT inputs, 1 each) × 1       AO-C       V-P         9       Image: Contrast output (CT and VT inputs, 1 each) + voltage pulse output (CT and VT inputs, 1 each) + v		3									Integrated-mounting kit included *1							
1       I		4										Standard mounting	Slot A4					
Image: Stand Point Stand S														1		SIO	t A4	
0       Image: State 4         1       Image: State 4 <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>1</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>A</td> <td></td>							1									A		
								•						1	Mana	Slot B4		
<ul> <li>Image: Sample block implementations for model No. and slot positions</li> <li>Digits 6-9 &amp; slot positions</li> <li>Example for CTGAH1CC000</li> <li> <ul> <li>Image: Sample block implementations for model No. and slot positions</li> <li>Digits 6-9 &amp; slot positions</li> <li>Example for CTGAH1CC000</li> <li>Image: Sample for CTGAH1CC000</li> <li>Imag</li></ul></li></ul>								0										
M       Motor drive output (with MFB input)       MOTOR         Image: Sample block implementations for model No. and slot positions       Sata 1       Sata 1       Sata 1         Digits 6-9 & slot positions       Example for C7GA411C0000       Image: Control output (CT and VT inputs, 1 each) × 1       AO-C         V       V       Voltage pulse output (CT and VT inputs, 1 each) + voltage pulse output (2 T inputs) × 1       V-P         Ingits 6-9 & slot positions       Example for C7GA411C0000       Image: Control output (CT and VT inputs, 1 each) + voltage pulse output (2 T inputs) × 1       AO-C         Image: Control output (T and VT inputs, 1 each) + voltage pulse output (2 T inputs) × 1       AO-C       HMI2         Image: Control output (T and VT inputs, 1 each) + clock (with battery)       AO-C       HMI2         Image: Control output (T and VT inputs, 1 each) + clock (with battery)       AO-C       HMI2         Image: Control output (T and VT inputs, 1 each) + clock (with battery)       AO-C       HMI2         Image: Control output (T and VT inputs, 1 each) + clock (with battery)       AO-C       HMI2         Image: Control output (T and VT inputs, 1 each) + clock (with battery)       AO-C       HMI2         Image: Control output (T and VT inputs, 1 each) + clock (with battery)       AO-C       HMI2         Image: Control output (T and VT inputs, 1 each) + clock (with battery)       AO-C       HMI2							I	1								Clote A2	2 02 2	
• Sample block implementations for model No. and slot positions   Digits 6-9 & slot positions Example for CTGA411CCDDO   A B   Digit 9 1   2									M						Mater drive output (with MED input)	SIULS AZ-	-3, D2-3	
<ul> <li>Sample block implementations for model No. and slot positions</li> <li>Digits 6–9 &amp; slot positions</li> <li>Example for C7GA411CC0000</li> <li> <ul> <li></li></ul></li></ul>									IVI							Slot A 1		
<ul> <li>Sample block implementations for model No. and slot positions</li> <li>Digits 6-9 &amp; slot positions</li> <li>Example for CTGA411CCODO</li> <li>A B</li> <li>Digits 6-1</li> <li>C</li> <lico< li=""></lico<></ul>										0					None	SIULAT	301 81	
<ul> <li>Sample block implementations for model No. and slot positions</li> <li>Digits 6-9 &amp; slot positions</li> <li>Example for C7GA411CC0D00</li> <li>A B</li> <li>Digit 9</li> <li>C</li> <li>C</li></ul>				h la	- I.: :		4 .			C C					Current output (CT and VT inputs 1 each) x 1	AO-C		
for model No. and slot positions       Example for C7GA411CC0D00       Voltage pulse output (2 or inputs) A1       Voltage pulse output (2 or inputs) A0-C       V-P         Digits 6-9 & slot positions       Example for C7GA411CC0D00       A       B       Current output (CT and VT inputs, 1 each) + voltage pulse output (2 or inputs) A0-C       HMI2         A       B       A       B       Current output (CT and VT inputs, 1 each) + voltage pulse output (2 or inputs) A0-C       HMI2         L       Current output (CT and VT inputs, 1 each) + voltage pulse output (2 or inputs) A0-C       Clock         M       C       O       None         U       O       None       O         D       With inspection report       V       O         Y       With traceability certificate       O       O         O       AC power. CE, KC, GB-compliant       O       O       No special support         V       With traceability certificate       O       No special support       V         V-P       Voltage pulse       Voltage pulse output (12 V DC) × 1       V-P       Voltage pulse       Voltage pulse output (12 V DC) × 1         *1. A rear-mounting bracket and a dedicated cable for connecting the display unit are       AO       A       A       Alalog Input       Full-multi range (thermocouple, RTD, DC current, DC voltage) inp	• 58	amp	DIE	DIO	ск іт	piem	nenta	ation	IS	v					Voltage pulse output (2 CT inputs) x 1	V-P		
Digits 6-9 & slot positions       Example for C7GA411CC0D00       Image: Control output (CT and VT inputs, 1 each) + additional display unit       AO-C       HMI2         A       B       A       B       A       B       O       None         Digit 9       1       0       None       O       None         D       With inspection report       V       V       With inspection report         Y       With inspection report       V       O       AO-C       Clock         Digit 8       O       None       O       None       O       None         D       With inspection report       V       V       With traceability certificate       O       None         D       D C power. CE, KC, GB-compliant       O       No special support       O       None         Init 4       A       A       O       Accord       None       O       Accord       O         Digit 6       Digit 7       A       B       O       Accord       None       O       Accord       O         VP       Oight 8       O       Accord       O       Accord       O       Accord       O         Vigit 6       Digit 7       A       Al       Ala	fo	r m	od	el N	o. an	d slo	ot po	sitio	ns	N					Current output (CT and VT inputs 1 each) + voltage pulse output (2 CT inputs)	AO-C	V-P	
Digit 6 O d side positions       A B       A       B       A       B       A       Current output (CT and VT inputs, 1 each) + clock (with battery)       AO-C       Clock         Digit 9       1       0       None       0       None       0       AO-C       Clock         Digit 9       1       0       AO-C       Clock       0       None       0       AO-C       Clock         Digit 9       1       0       AO-C       Clock       0       None       0       None       0       None       0       None       0       0       None       0       No       0       No       0       No       0       No       0       No       0       No       0<	Digits 6–9 & slot positions Example for C7GA411CC0D00		000	G					Current output (CT and VT inputs 1 each) + additional display unit	AO-C	HMI2							
A       B       A       B       B       A       B       O       None         Digit 9       1       1       0       None       None       O       None         U       0       None       0       None       O       None         U       0       A       0       None       O       None         U       0       A       O       A       O       None       O         U       0       A       O       A       O       A       O       A       O       O       A         U       0       No pecial support       O       No special suport			500	L					Current output (CT and VT inputs, 1 each) + clock (with battery)	AO-C	Clock							
Digit 9       1       1         2      Digit 8       2         3      Digit 8       2         3	A B A B				0				None									
Digit 9       1       1         2      Digit 8       2         3      Digit 8       2         3			i i		-	Г			1			0			None			
Y       With traceability certificate         0       AC power. CE, KC, GB-compliant         0       D power. CE, KC, GB-compliant         0       No special support         1       AI         4       AI         5       Block Name         0       No special support             *1. A rear-mounting bracket and a dedicated cable for connecting the display unit are       AI             *1. A rear-mounting bracket and a dedicated cable for connecting the display unit are       AI		'	Digit	9 (	1			10				D			With inspection report			
<ul> <li>*1. A rear-mounting bracket and a dedicated cable for connecting the display unit are</li> <li>*1. A rear-mounting bracket and a dedicated cable for connecting the display unit are</li> <li>(2)</li> <li>(3)</li> <li>(4)</li> <li>(4)</li> <li>(5)</li> <li>(6)</li> <li>(7)</li> <li>(7)</li> <li>(7)</li> <li>(8)</li> <li>(9)</li> <li>(9)</li> <li>(10)</li> <li>(10)</li></ul>					-							Y With traceability certificate						
D       DC power. CE, KC, GB-compliant         Digit 6       Digit 7       AI       AI         AI       AI       AI       AI       AI         Y       Arear-mounting bracket and a dedicated cable for connecting the display unit are       Symbol       Block Name       Description         AI       V-P       Voltage pulse output       Full-multi range (thermocouple, RTD, DC current, DC voltage) input × 1         V-P       Voltage pulse output       Voltage pulse output (12 V DC) × 1       Two input terminals for the current transformer (CT) for detecting heater burnout, overcurrent, and short circuit are included.*3				•   `	2			1 2			0				AC power. CE, KC, GB-compliant			
Symbol     Block Name     Description       AI     AI     AI     AI       *1. A rear-mounting bracket and a dedicated cable for connecting the display unit are     AI     AI		[	igit	°1/	3	[-	MOTOR		1				D		DC power. CE, KC, GB-compliant			
Digit 6 Digit 7       AI       Analog Input       Full-multi range (thermocouple, RTD, DC current, DC voltage) input × 1         *1. A rear-mounting bracket and a dedicated cable for connecting the display unit are included for connecting the display unit are       V-P       Voltage pulse output (12 V DC) × 1 Two input terminals for the current transformer (CT) for detecting heater burnout, overcurrent, and short circuit are included.*3				`	<u> </u>									0	No special support			
Al     Analog Input     Full-multi range (thermocouple, RTD, DC current, DC voltage) input × 1       *1. A rear-mounting bracket and a dedicated cable for connecting the display unit are     V-P     Voltage pulse output (12 V DC) × 1 Two input terminals for the current transformer (CT) for detecting heater burnout, overcurrent, and short circuit are included.*3		Digi	t 6 Di	igit 7 <	4		AI	4		Symbo		Block	Namo		Description			
*1. A rear-mounting bracket and a dedicated cable for connecting the display unit are included in the second secon									-	Symbo			Name	; 1		innut v	. 1	
*1. A rear-mounting bracket and a dedicated cable for connecting the display unit are to be the base of the three terminals for the current transformer (CT) for detecting heater burnout, overcurrent, and short circuit are included.*3									-		An	alog ir	iput	1	ull-multi range (thermocouple, RTD, DC current, DC voltage) input × 1			
*1. A rear-mounting bracket and a dedicated cable for connecting the display unit are burnout, overcurrent, and short circuit are included.*3										V-P	VO	itage p	uise	-	/oltage pulse output (12 V DC) × 1			
cable for connecting the display unit are bulliout, overcurrent, and short circuit are included.	*1. A	<ol> <li>A rear-mounting bracket and a dedicated</li> </ol>						oui	ιραι			two input terminals for the current transformer (CT) for detection	ig neat	er				
	ca	cable for connecting the display unit are				-		-				purnout, overcurrent, and short circuit are included.*3						
included with the product. AO-C Analog current Current output (4–20 mA DC / 0–20 mA DC) × 1	included with the product.						AO-C	An	alog ci	urrent		Current output (4–20 mA DC / 0–20 mA DC) × 1						
2. PVZ can be switched for use as RSP1. Output input terminals for the current transformer (CL) for measuring current and the uniform for the current transformer (CL) for measuring current and	*2. PV2 can be switched for use as RSP1.							oui	tput			nput terminals for the current transformer (CT) for measuring (		and				
5. Current transformer (CT) and voltage trans-	<ol> <li>Current transformer (CT) and voltage trans-</li> </ol>					H						The voltage transformer (v r) for measuring voltage are include						
*4. Additional display unit is sold separately. MOTOR Motor drive output Motor drive output (100/200 V AC) Direct (OPEN) output, reverse (CLOSE) output, and motor feedback (MFB) inputs are included.	*4. Ac	former (VT) are not included. 4. Additional display unit is sold separately.						MOTO	R	otor dri	ve out	put I	Notor drive output (100/200 V AC) Direct (OPEN) output, reverse (CLOSE) output, and motor feedback (MFB) inputs are included.					
HMI2 Additional display Connector for the second display unit *4										HMI2	Ad	ditiona it	l displ	ay (	Connector for the second display unit *4			
unit										Clock	Clo	ock fun	oction	(	Clock (available for CDS and health index) with a battery			
unit										Clock	Clo	ock fun	oction	(	Clock (available for CDS and health index) with a battery			

# Model selection (display unit)

#### Example: C7D-400D00 Main unit Other Instal-lation method Add'l spec. Op-tion 1 Op-tion 2 Add'l proc. Special support Basic model No. Description 3 6 9 10 1 2 4 5 7 8 С 7 D Additional display unit 3 Integrated-mounting kit included \*1 Standard mounting 4 0 None 0 None 0 None With inspection report D 0 CE, KC, GB-compliant \*1. A rear mounting bracket is included. 0 No special support

# Accessories (sold separately)

Name	Model No.
SLP-C7 Smart Loader Package (free version) *	SLP-C7FJ91
SLP-C7 Smart Loader Package (paid version)	SLP-C7-J91
Current transformer (5.8 mm in diameter)	QN206A
Current transformer (12 mm in diameter)	QN212A
Voltage transformer (for 200 V AC)	81406725-003

### Model No. and loop type

The following table shows the possible combinations of model No. and loop type with regard to analog input.

- OK : Combination is possible
  - : Combination is not possible

For possible combinations, slots for AI blocks and loop PVs or RSPs assigned to the blocks are shown.

PV1: LOOP1 PVPV2: LOOP2 PVPV3: LOOP3 PVPV4: LOOP4 PVRSP1: LOOP1 RSP

RSP2 : LOOP2 RSP

Not used : The AI block slot exists but is not assigned to the PV or RSP of a loop.

Loop type	6th and 7th digits of the model No. (C7GA )										
Loop type	10	20	11	21	22						
0: 1 loop	OK	OK	OK	OK	OK						
PV1 ↓ PID ↓ MV1	A4: PV1	A4: PV1 A3: Not used	A4: PV1 B4: Not used	A4: PV1 A3: Not used B4: Not used	A4: PV1 A3: Not used B4: Not used B3: Not used						
1: 1 loop + 1 RSP PV1 RSP1 PID MV1	_	OK A4: PV1 A3: RSP1	_	OK A4: PV1 A3: RSP1 B4: Not used	OK A4: PV1 A3: RSP1 B4: Not used B3: Not used						
2: 2 loops PV1 PV2 PID PID MV1 MV2	_	_	OK A4: PV1 B4: PV2	OK A4: PV1 A3: Not used B4: PV2	OK A4: PV1 A3: Not used B4: PV2 B3: Not used						
3: 2 loops + 1 RSP PV1 RSP1 PV2 PID PID PID PID WV1 MV2		_		OK A4: PV1 A3: RSP1 B4: PV2	OK A4: PV1 A3: RSP1 B4: PV2 B3: Not used						
4: 2 loops + 2 RSPs PV1 RSP1 PV2 RSP2 PID PID MV1 MV2					OK A4: PV1 A3: RSP1 B4: PV2 B3: RSP2						
5: 3 loops PV1 PV2 PV3 PID PID PID WV1 WV2 WV3				OK A4: PV1 A3: PV3 B4: PV2	OK A4: PV1 A3: PV3 B4: PV2 B3: Not used						
6: 3 loops + 1 RSP PV1 PV2 RSP2 PV3 PID PID PID PID MV1 MV2 MV3					OK A4: PV1 A3: PV3 B4: PV2 B3: RSP2						

Loontune		6th and 7th digits of	of the model No. (C7	GA)	
соор туре	10	20	11	21	22
7: 4 loops PV1 $PV2$ $PV3$ $PV4PID$ $PID$ $PID$ $PID$ $PIDWV1$ $WV2$ $WV3$ $WV4$		_			OK A4: PV1 A3: PV3 B4: PV2 B3: PV4
8: 1 loop + 1 RSP PV1 RSP1 PID MV1	_	_	OK A4: PV1 B4: RSP1		
9: Internal cascade	_	_	OK A4: PV1 (master) B4: PV2 (slave)	OK A4: PV1 (master) A3: None B4: PV2 (slave)	OK A4: PV1 (master) A3: None B4: PV2 (slave) B3: None
10: Internal cascade + 1 loop PV1 PV2 PV3 PID PID PID RSP2 MV2 MV3	_	_		OK A4: PV1 (master) A3: PV3 B4: PV2 (slave)	OK A4: PV1 (master) A3: PV3 B4: PV2 (slave) B3: None
11: Internal cascade + 2 loops PV1 PV2 PV3 PV4 PID PID PID PID PID RSP2 MV2 MV3 MV4		_			OK A4: PV1 (master) A3: PV3 B4: PV2 (slave) B3: PV4

### **!** Handling Precautions

• The value of unused AI blocks is not displayed. To display a PV value for monitoring even if there is no need to control it, select a loop type that has the AI block assigned to a PV. Ex.: if model No. digits 6–7 are "11," select a 2:2 loop, not a 0:1 loop. In such a case, since the PV is actually not controlled, it is not necessary to set the analog current output block or DI/DO block to output MV.

# **External Dimensions and Mounting**

#### Standard mounting



#### Integrated mounting

(Unit: mm)



# **Part Names and Functions**

#### • Display unit



· Integrated mounting bracket (included with integrated mounting models)



# **Terminal Connections**





1

2

3

4

(5



#### DO wiring example

Main unit

Power supply terminals



(4)

(5)

(6)

#### Full multiple inputs



RS-485



Current output

СТ

VT

mΑ



Voltage pulse output



MFB (Y)

MFB (T)

MFB (G)

Motor drive relay

MFB

3

Close



 $\overline{A}$ 

B



# I/O isolation





- No isolation
- \*1. Blocks are functionally isolated from one another.
- \*2. The power block (AC) and the motor block (relay output) have reinforced insulation for isolation from all other circuits.

### **Wiring Precautions**

Before touching the main unit or display unit, or removing/ inserting cables, touch a grounded panel to discharge static electricity from your body.

#### Power input

AC power

- 1: AC power supply live line
- 2: AC power neutral line
- 3: Frame ground

DC power

- 1: DC power +
- 2: DC power -
- 3: Frame ground

#### **!** Handling Precautions

- Before touching the power input terminal box, shut off the input power.
- After completing the work, be sure to mount the cover on the power input terminal block.

Note: Applicable crimp terminal for power input: Crimp terminal for M4 (8.5 mm or less wide). Proper tightening torque: 1.4 N·m

### DI/DO (digital inputs and outputs)

- : NC (not connected)
- N1–7 : DI/DO 1–7 (DI and DO can be switched by changing the setting.)
- V- : COM (common terminal)

#### RS-485 (RS-485 communication port)

- C1 : —— DA (Data+)
- $\begin{array}{ccc} C2: & & \\ C3: & & \\ \end{array}$  Terminating resistor
- C4 : \_\_\_\_ DB (Data-)
- $C_{4}$ : DB (Data-)  $C_{5}$ : ----- SG

#### ··· ·· -

- Handling Precautions
  - Connect a terminating resistor (120  $\Omega,$  1/2 W) to both ends of the communication line.
  - To connect two terminals (e.g., SG + another) together, use a crimp terminal for two wires.

#### Al block (analog input)

Current input Voltage input Thermocouple input RTD input

1.	mA+	1.	1			1.	
1.		1.	1			1.	
2 :		2: V+ —	7 2	2:		2:	
3 :	(1)	3:	3	3:		3:	C
4 :	Ť	4 :	Τ 4	1:	+	4:	B – T
5:		5:	4	5.	^	5.	

Allowable input voltage

Current input: -1.5 to +1.5 V Voltage input: -15 to +15 V

Thermocouple input: -1.5 to +1.5 V

# AO-C block (current outputs with CT and VT inputs)

- 1 : CT input
- 2 : CT/VT common
- 3 : VT input
- 4 : Current output +
- 5 : Current output -
- Maximum allowable input
  - CT: 90 mA and 130 mA peak (AC)
    - 1 V and 1.4 V peak (AC)
  - VT: 18 V and 26 V peak (AC)

Transient overvoltage

CT: supply voltage + 250 V

#### **!** Handling Precautions

• If a current transformer is used for a UL-compliant model, the transformer must be compliant with UL 2808 (categories XOBA and XOBA7). Do not use an uncertified current transformer.

# V-P block (voltage pulse outputs and 2 CT inputs)

- 1 : CT1
- 2 : Common
- 3 : CT2
- 4 : Voltage pulse output +
- 5 : Voltage pulse output -
- Maximum allowable input

CT: 90 mA and 130 mA peak (AC)

1 V and 1.4 V peak (AC)

Transient overvoltage

CT: supply voltage + 250 V

Load current:

Voltage pulse output: 25 mA max.

# MOTOR block (motor drive relay output: with MFB inputs)

1 2 3	: OPEN : Common : CLOSE	Contact voltage: 250 V AC / 125 V DC max.
4 5 6	: MFB (Y) : MFB (T) : MFB (G)	Potentiometer for motor feedback (100 to 2500 $\Omega$ )

# Recommended ferrules

Manufacturer : Phoenix Contact Crimp tool : CRIMPFOX 6

#### DI/DO, RS-485, AI, AO-C, V-P

Designation	Order Nos.	Cross section (mm <sup>2</sup> )	Note
AI 0,25-8 YE	3203037	0.25 (AWG24)	With insulation sleeve
AI 0,34-8-TQ	3203066	0.34 (AWG22)	With insulation sleeve
AI 0,5-8 WH	3200014	0.50 (AWG20)	With insulation sleeve
AI 0,75-8 GY	3200519	0.75 (AWG18)	With insulation sleeve
A1-8	3202517	1.00 (AWG18)	Without insulation sleeve Used to crimp two JKPEV-S-2Px0.5SQ together.
A1,5-7	3200263	1.50 (AWG16)	Without insulation sleeve Used to crimp two JKPEV-S-2Px0.75SQ together.
AI-TWIN 2X0, 5-8 WH	3200933	0.50 (AWG20)	With insulation sleeve, twin
AI-TWIN 2X0, 75-8 GY	3200807	0.75 (AWG18)	With insulation sleeve, twin

#### MOTOR

Designation	Order Nos.	Cross section (mm <sup>2</sup> )	Note	
AI0,75-8 BU	3200027	0.75 (AWG18)	With insulation sleeve	
AI1-8 RD	3200030	1.00 (AWG18)	With insulation sleeve	
Al1,5-8 RD	3201136	1.50 (AWG16)	With insulation sleeve	
AI2,5-10 BU	3202533	2.00 (AWG14)	With insulation sleeve	

#### HMI (display unit)

Designation	Order Nos.	Cross section (mm <sup>2</sup> )	Note
AI0.25-6 YE	3203024	0.25 (AWG24)	For display connector, without insulation sleeve

### USB connection

Connect the device to the PC using a USB-to-MicroUSB (type A or B) cable.

#### **!** Handling Precautions

 Connection and disconnection of the MicroUSB is hazardous because there is a power terminal nearby. Be sure to turn off the power before connecting or disconnecting the cable.

Note: Use a data communication cable.

### Inserting or removing a microSD memory card

Insert the microSD memory card all the way inside. Pushing on the memory card lightly will release it, enabling you to remove the card.

#### **!** Handling Precautions

- Do not insert or remove a memory card while the indicator near the connector is flashing.
- Connection and disconnection of a microSD memory card is hazardous because there is a power terminal nearby. Be sure to turn off the power before connecting or disconnecting the card.

### Connecting the LAN cable for Ethernet

Use a Cat5E or higher LAN cable to make the connection.

# Connecting the main unit to the display unit using a cable

#### For standard mounting

Use a Cat5E or higher straight LAN cable to make the connection. (Cat5E, T568A, or T568B wiring. Both ends use RJ45 plug (8P8C modular).)

- \*1. A 4-core LAN cable cannot be used.
- \*2. If the length of the cable between the main unit and the display unit is from 30 m to 100 m, an external power source must be connected for the display unit.

#### • Wiring for integrated mounting

Insert the rod-shape crimp terminal lug of the wires with the specified colors of the included cable into the terminal block of the display unit..

1: White/orange	4: White/green
2: Blue	5: Green
3: White/blue	6: Brown

# **Operation Check**

After connecting the main unit to the display unit and turning on the power, a display will appear.

The display that first appears on the screen after power-on is called the initial display.

Display change button : Switches the display. HOME button : Returns to the initial display.

MENU/Key lock button:

Displays the menu. Pressing the button for four seconds or longer locks the keys. Disabling the key lock is then the only operation permitted. Pressing the button again for four seconds or longer disables the key lock.

# Troubleshooting

#### Model number and serial number

The model number and serial number are printed on the top of the main unit near the front of the unit. Have these numbers ready before contacting us.

### Problems in installation

First, check the following regarding wiring:

- Connectors are securely inserted into the ports.
- · Connectors are inserted into the right ports.
- Wires are properly connected to the power supply terminal block.

#### Power is not turned on

Status	Countermeasures	
The status indicator on the main unit is off.	Check the the power input connections and voltage.	
The status indicator on the main unit is lit green or the power indicator on the display unit is off.	Standard mounting: Check the LAN cable (8-core straight). Check the connectors. Integrated mounting: Check if the wiring on the back of the display unit is correct. Check connec- tors on the main unit.	
The power indicator on the display unit is lit green and the LCD remains black.	There may be a problem with the device. Please contact us.	
The status indicator on the main unit is lit red.	There may be a problem with the device. Please contact us.	

#### Blurry display

A thin film is applied on the protection sheet of the display for protection during transportation. Please remove the protective film.

Alarms (the status indicator is blinking red) Please refer to the user's manual.

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