## C7G Multi-loop Controller with Multifunction Display

## Overview

The C7G multi-loop controller with multifunction display (hereafter also called simply "this device") can calculate diagnostic parameters, known collectively as the health index, that help to predict failure of other equipment, in addition to calculations for PID (proportional, integral and derivative) control of process variables such as temperature, pressure, flow rate, pH , and liquid level.
The controller consists of a display unit with a 3.5-inch QVGA LCD and a touch panel, as well as a main unit capable of controlling up to four loops with an input sampling cycle of 10 ms and an indication accuracy of $\pm 0.1 \% \mathrm{FS}$.
The display unit and main unit can be installed separately for installation flexibility.
A wide variety of interfaces, including Ethernet, RS-485 serial communication, microSD memory card, Micro USB port, and 7 digital input/outputs are provided as standard features. Setup, operation, and monitoring can be easily accomplished using the display unit and Smart Loader Package.
This controller is compliant with the IEC Directive and is CE marked.

## Features

- High-speed and high-accuracy control is available with an input sampling cycle as fast as 10 ms and an indication accuracy of $\pm 0.1 \%$ FS. Process data can be stored with the compact data storage function (microSD card).
- Diagnostic and management information is created with our unique process data-processing technology (the health index function).
- One module can execute PID control for up to 4 loops.
- Various information is displayed on a 3.5-inch QVGA LCD with easy touchscreen operation.

- The display unit and main unit can be installed separately Standard distance: less than 30 m If display unit is separately powered: 30 to 100 m
- Protective structure of display face: IP67
- Ethernet and RS-485 serial communications (Modbus) are supported as standard features.
- For setup and file management the SLP-C7 Smart Loader Package can be used.
- Parameters can be downloaded to the C7G when it is powered by the USB bus power function when the MicroUSB port and the PC are connected with a USB cable.


## C7G Basic Functional Blocks



Specifications

| Analog Input block |  | Input type | Full multi-range for thermocouple, resistance temperature detector (RTD), DC current, and DC voltage |
| :---: | :---: | :---: | :---: |
|  |  | No. of control loops | 4 loops max. (configurable by the loop type setting) |
|  |  | Range type | F Table 1, "Input types and ranges" (p.8) |
|  |  | Sampling cycle | $10 \mathrm{~ms}, 50 \mathrm{~ms}, 100 \mathrm{~ms}$ (factory default: 50 ms ) |
|  |  | Burnout | Depends on the input range ( $\mathrm{F}^{\mathbf{\beta}}$ Table 1, "Input types and ranges," p. 8) |
|  |  | Over-range judgment | Below -10\% or above $110 \%$ of the range |
|  |  | Decimal point position | 0 to 4 digits after the decimal point are displayed. Values are displayed so that the entire value does not exceed 5 digits. (Note: Effective resolution depends on the range.) |
|  | Thermocouple | Reference contact compensation accuracy | $\pm 0.5^{\circ} \mathrm{C}$ (ambient temperature 21 to $27^{\circ} \mathrm{C}$, under standard conditions) <br> $\pm 1.5^{\circ} \mathrm{C}$ (ambient temperature 0 to $50^{\circ} \mathrm{C}$, under standard conditions except for ambient temperature) |
|  |  | Reference contact compensation method | Compensation within the C7G |
|  |  | Input bias current | $0.12 \mu \mathrm{~A}$ max. (under standard conditions) *From the positive (+) terminal |
|  |  | Allowable input voltage | -1.5 to +1.5 V |
|  | Resistance temperature detector (RTD) | Measuring current | 1.0 mA (typical, from terminals A and B, under standard conditions) |
|  |  | Allowable wiring resistance | $85 \Omega$ max. (per wire) |
|  |  | Effect of wiring resistance | $0.013^{\circ} \mathrm{C} / \Omega$ |
|  | DC voltage DC current | Input bias current | 0 to 10 V range : $10 \mu \mathrm{~A}$ max. (under standard conditions) $1-5 \mathrm{~V}$ or $0-5 \mathrm{~V}$ range: $5 \mu \mathrm{~A}$ max. (under standard conditions) |
|  |  | Allowable input voltage | DC voltage input: -15 to +15 V DC current input: -1.5 to +1.5 V |
|  |  | Input impedance | DC voltage input: $1 \mathrm{M} \Omega \mathrm{min}$. DC current input: $50 \Omega$ |
|  |  | Scaling | $-32000 \text { to }+32000 \mathrm{U}$ <br> (Max. 5 digits within the above range, max. 4 digits after the decimal point, reverse scaling possible) |
| Display unit (included) (C7D-xxxxxx) |  | Screen specifications | 3.5-inch QVGA LCD |
|  |  | Status display (LED): | 1 (power) |
|  |  | Operation buttons | Touchscreen (resistive) and 3 hardware buttons |
|  |  | Display power source | Main unit (if distance from connector on the main unit or connector on the additional display unit block to the display unit is less than 30 m ) <br> 5 V DC external power supply (if distance from connector on the main unit or connector on the additional display unit block to the display unit is 30 to 100 m ) |
|  |  | Protection rating | IP67 (front of display unit only) |
|  |  | Interface language | English/Japanese (switchable) |
|  |  | Service life of LCD | 5 years (at ambient temperature of $25^{\circ} \mathrm{C}$ and brightness setting 4, for half-life of backlight brightness) |
| DI (digital input)/ DO (digital output) |  | No. of I/Os | 7 max. (select DI, DO, or TP by setting), shared common <br> Note: TP (time proportioning output) can be selected for DI/DO terminals 4 to 7 . |
| block | Digital input | Compatible output type | Non-voltage contacts or open collector (sink type) |
|  |  | Open terminal voltage | 7 V max. |
|  |  | Terminal current (when shorted): | 1 mA (under standard conditions) |
|  |  | On-state contact resistance (no-voltage contact) | $500 \Omega$ max. (under standard conditions) |
|  |  | Off-state contact resistance (no-voltage contact) | $100 \mathrm{k} \Omega$ max. (under standard conditions) |
|  |  | Allowable on-state residual current for open collector | 1 V max. (under standard conditions) |
|  |  | Allowable off-state residual current for open collector | $100 \mu \mathrm{~A}$ max. (under standard conditions) |
|  |  | Input sampling cycle | 10 ms |
|  |  | Minimum pulse width for ON detection | $20 \mathrm{~ms} \mathrm{min}. \mathrm{(for} 10 \mathrm{~ms} \mathrm{sampling} \mathrm{cycle)}$,40 ms min . (50 or 100 ms sampling cycle) |
|  |  | Function assignment | RUN/READY mode selection, AUTO/MANUAL mode selection, LSP/RSP mode selection, SP group selection, CDS stop/start, etc. |


| DI (digital input)/ DO (digital output) block | Digital output | Output method | Open collector (sink type) |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | Load voltage | 4.5 to 28.8 V DC |  |
|  |  | Maximum load current | 100 mA for each terminal |  |
|  |  | Overcurrent detection | 130 mA or more <br> When an overcurrent is detected, the output is turned OFF, and the status is checked every 5 seconds. If the status returns to normal, the output returns to normal automatically. |  |
|  |  | On-state residual voltage | 0.5 V max. (under standard conditions) |  |
|  |  | Off-state leak current | $100 \mu \mathrm{~A} \mathrm{max}$. (under standard conditions) |  |
|  |  | Function assignment | Select an event status or a standard bit code |  |
|  | Time proportional output | Output method | Same as digital output |  |
|  |  | Number of outputs | 4 max. (DI/DO terminals 4 to 7) |  |
|  |  | Min. OFF time / ON time | In time proportional cycle shorter than $10 \mathrm{~s}: 1 \mathrm{~ms}$ In time proportional cycle of 10 s or longer: 250 ms |  |
| Control unit |  | Control operation | PID control (reverse action, direct action, heating and cooling action), ON/OFF control (reverse action, direct action) |  |
|  |  | PID Control | Proportional band (P) | 0.1 to 3200 \% ( 5 digits max. within this range, 4 digits max. after the decimal point) |
|  |  | Integral time (I) | 0 to 32000 s ( 5 digits max. within this range, 4 digits max. after the decimal point) <br> No integral calculation when the setting is 0 . |
|  |  | Derivative time (D) | 0 to 32000 s ( 5 digits max. within this range, 4 digits max. after the decimal point) <br> No derivative calculation when the setting is 0 . |
|  |  | MV limits | -10 to $+110 \%$ ( 5 digits max. within this range, 4 digits max. after the decimal point) |
|  |  | Manual reset | -10 to $+110 \%$ ( 5 digits max. within this range, 4 digits max. after the decimal point) |
|  |  | Number of PID groups | 8 groups per loop |
|  |  | PID group selection | SP group interlocking system |
|  |  | MV change limit | 0 to $10000 \% / \mathrm{s}$ ( 5 digits max. within this range, 4 digits max. after the decimal point) <br> No limit when the setting is 0 . |
|  |  | Auto-tuning | PID automatic setting using the limit cycle method |
|  |  | Control cycle | Same as sampling cycle |
|  |  | $\begin{aligned} & \text { SP } \\ & \text { (LSP: Local SP) } \end{aligned}$ | Number of LSP groups | 8 groups per loop |
|  |  | SP ramp unit | 0: s, 1: min, 2: h |
|  |  | Ramp up and down slopes | 0 to 32000 |
|  |  | Direct/reverse operation selection | Switchable |  |
|  |  | Heating/cooling control deadband | -100.0 to +100.0 \% |  |
| Analog input processing unit |  |  | Linear scaling low and high limits | -32000 to +32000 ( 5 digits max. within this range, 4 digits max. after the decimal point) |  |
|  |  | Filter | 0.0000 to 120.00 s |  |
|  |  | Ratio | 0.0010 to 10.000 |  |
|  |  | Bias | -32000 to +32000 (5 digits max. within this range, 4 digits max. after the decimal point) |  |
| Event functions |  |  | Operation type | PV high limit, PV low limit, PV high and low limits, deviation high limit, deviation low limit, deviation high and low limits, deviation high limit (final SP basis), deviation low limit (final SP reference), deviation high and low limits (final SP basis), SP high limit, SP low limit, SP high and low limits, MV high limit, MV low limit, MV high and low limits, MFB high and low limits, standard numerical code high limit, standard numerical code low limit, standard numerical code high and low limits, PV change rate, PV change rate high limit, PV change rate low limit, standard numerical code change rate high limit, standard numerical code change rate low limit, Alarm (state), READY (state), MANUAL (state), RSP (state), AT running (state), SP ramp running (state), control direct action (state), control with estimated MFB (state), timer (state) |  |
|  |  | Number of events | 16 |  |
|  |  | Main setting / subsetting | -32000 to +32000 (5 digits max. within this range, 4 digits max. after the decimal point) |  |
|  |  | Hysteresis | 0 to 32000 ( 5 digits max. within this range, 4 digits max. after the decimal point) |  |
|  |  | READY mode operation | Selectable from "continuation" and "forced OFF." |  |
|  |  | Direct/reverse | Select the polarity to turn ON/OFF in event output |  |
|  |  | Standby | 0 : None, 1: Standby, 2: Standby + standby when the SP is modified |  |
|  |  | On-delay time | 0 to 3200 s (4 digits max. within this range, 4 digits max. after the decimal point) |  |
|  |  | OFF-delay time | 0 to 3200 s (4 digits max. within this range, 4 digits max. after the decimal point) |  |
| Approximation by linearization |  | Number of groups | 8 |  |
|  |  | Breakpoints per group | 10 |  |
|  |  | Available for | Analog input, analog output, voltage pulse output |  |


| Analog current output block | Current output (1) | Type | 4-20 mA DC / 0-20 mA DC |
| :---: | :---: | :---: | :---: |
|  |  | Output type | Control output (MV), process value (PV), set value (SP), standard numerical code, etc. |
|  |  | Accuracy | 0.1 \% FS |
|  |  | Allowable load resistance | $600 \Omega$ max. |
|  |  | Output resolution | 1/16000 min. |
|  | CT (current) input <br> (1) | Recommended current transformer | QN206A (hole dia. $5.8 \mathrm{~mm}, 800$ turns), QN212A (hole dia. $12 \mathrm{~mm}, 800$ turns) Note: Not UL-certified |
|  |  | Measuring current range | 0.4-50.0 A AC, $50 / 60 \mathrm{~Hz}$ (peak current: $71 \mathrm{~A}, 800$ turns, 1 power wire loop) |
|  |  | Maximum allowable current | 70 AAC (peak current: 99 A max. with 800 turns and 1 pass of the power wire) |
|  |  | Indication accuracy | $\pm 1 \% \mathrm{FS} \pm 1$ digit (under standard conditions, CT accuracy is not included) |
|  |  | Indication resolution | 0.1 AAC |
|  |  | Indication update cycle | 100 ms |
|  | VT (voltage) input <br> (1) | Recommended voltage transformer | 81406725-003 <br> Note: Not UL-certified. |
|  |  | Voltage measurement range | 24 to $240 \mathrm{~V} \mathrm{AC}, 50 / 60 \mathrm{~Hz}$ (peak voltage: 339 V max.; recommended voltage: transformer primary side 200 V , secondary side 10 V ) |
|  |  | Maximum allowable voltage | 264 V AC (peak voltage: 373 V ; recommended voltage transformer primary side: 200 V , secondary side: 10 V ) |
|  |  | Indication accuracy | $\pm 1 \%$ FS $\pm 1$ digit |
|  |  | Indication resolution | 0.1 V AC |
|  |  | Input impedance | $160 \mathrm{k} \Omega$ (typ) |
|  |  | Indication update cycle | 100 ms |
| Voltage pulse output block | Voltage pulse output (1) | Output voltage | 12 V DC +15/-10 \% (under standard conditions) |
|  |  | Allowable current | 25 mA max |
|  |  | Load limit current | $30 \mathrm{~mA} \pm 10$ \% |
|  |  | OFF-state leak current | $100 \mu \mathrm{~A}$ max. (under standard conditions) |
|  |  | Output response time | $100 \mu$ s max. for $10 \leftrightarrow 90 \%$ of output voltage |
|  | CT (current) input (2) | Specifications | Same as CT (current) input for the analog current output block |
| Motor drive output block | Relay output OPEN CLOSE | Contact configuration | Switching between OPEN output and CLOSE output (with function for turning both outputs OFF at the same time) |
|  |  | Contact rating | $250 \mathrm{~V} \mathrm{AC} ,2 \mathrm{~A}(\cos \varphi=0.4) ; 24 \mathrm{~V} \mathrm{DC} ,2.5 \mathrm{~A}(\mathrm{~L} / \mathrm{R}=0.7 \mathrm{~ms})$ |
|  |  | Contact voltage | 250 V AC / 125 V DC max. |
|  |  | Service life | 100,000 cycles min. (at the rated specifications) |
|  |  | Minimum requirements for switching | 24 V DC, 40 mA |
|  |  | Interlock | With prevention of simultaneous ON if contact welding occurs |
|  | Motor feedback (MFB) input 1 | Allowed potentiometer resistance | 100 to $2500 \Omega$ (wiring resistance included) |
|  |  | Indication accuracy | $\pm 0.5$ \% FS (under standard conditions) |
|  |  | Sampling cycle | 100 ms |
|  |  | Operation at burnout | Y line break: downscale Other line break: upscale |
| Clock block (with battery) |  | Clock function | Hours, minutes, seconds, calendar (years 2000 to 2099, supports leap years) |
|  |  | Clock accuracy | Monthly error: $\pm 65 \mathrm{~s}$ (under standard conditions) |
|  |  | Service life | 10 years (battery life when not energized, under standard conditions) |
|  |  | Built-in battery | Lithium battery |
|  |  | Block replacement | Possible (optional parts sold separately) |
| Additional display unit block |  | Number of connectable units | 1 |
|  |  | Connector | RJ-45 |
| External communication | Ethernet | Transmission line type | Compliant with IEEE 802.3u 100BASE-TX (FastEthernet) |
|  |  | Communication method | Full duplex |
|  |  | No. of connections | 3 (for Modbus/TCP and loader communication via Ethernet) |
|  |  | Transmission speed | 100 Mbps max. |
|  |  | No. of physical ports (connectors) | 1 (RJ-45) |
|  |  | Cable | UTP cable (4P) Cat 5e min. (straight) (ANSI/TIA/EIA-568-B both ends) |
|  |  | Protocol: | Modbus/TCP, Mitsubishi SLMP (3E) (for PLC link communication) |


| External communication | RS-485 communication | Signal level | RS-485-compliant |
| :---: | :---: | :---: | :---: |
|  |  | Network | Multidrop (up to 31 slave stations for 1 host station) |
|  |  | Communications/synchronization type | Half-duplex, start-stop synchronization |
|  |  | Maximum cable length | 500 m |
|  |  | No. of communication wires | 3-wire system |
|  |  | Transmission speed | 9600, 19200, 38400, 57600, 115200 bps |
|  |  | Terminating resistor | External (120 $\Omega$, $1 / 2 \mathrm{~W}$ min.) |
|  |  | Data length | 8 bits |
|  |  | Stop bits | 1 or 2 bits |
|  |  | Parity bit | Even parity, odd parity, or no parity |
|  |  | Protocol | Modbus/RTU |
|  | Loader communication | Dedicated PC loader | SLP-C7FJ91 (free version), SLP-C7-J91 (paid version) |
|  |  | Cable | USB-to-Micro-USB (Type A/B) cable (USB 2.0 supported, 5 m max.) or Ethernet cable |
|  |  | Power supply | When connected with a USB cable, the device can be powered by the PC and parameters can be changed. |
| Data storage |  | SD | microSD/SDHC-compliant (4GB), for the compact data storage and health index functions |
| General specifications |  | Backup memory | EEPROM (durability: 1 million erase-write cycles max., for parameter settings) |
|  |  | Power consumption | AC models: 25 VA 10 W max. DC models: 12 W max. |
|  |  | Power-on inrush current | 25 A max./10 ms max. |
|  |  | Start delay at power-on | 10 s max. (the time until normal operation begins under standard conditions) |
|  |  | Allowable transient power loss | AC models: 20 ms min . DC models: 5 ms min . |
|  |  | Insulation resistance | $20 \mathrm{M} \Omega$ min. (between power supply terminal (\#1 or \#2) and frame ground terminal (\#3), with a 500 V DC megger) |
|  |  | Dielectric strength | AC models: <br> 1500 V AC for 1 min <br> Between AC power supply terminal (\#1 or \#2) and frame ground terminal (\#3) <br> Between AC power supply terminal (\#1 or \#2) and secondary terminals (except for <br> motor block output terminals (\#1 to \#3)) <br> Between AC power supply terminal (\#1 or \#2) and motor block terminals (\#1 to \#3) <br> Between motor block output terminals (\#1 to \#3) and frame ground terminal (\#3) <br> Between motor block output terminals (\#1 to \#3) and secondary terminals other than motor block output terminals (\#1 to \#3) <br> DC models <br> 1500 V AC for 1 min <br> Between motor block output terminals (\#1 to \#3) and frame ground terminal (\#3) Between motor block output terminals (\#1 to \#3) and DC power supply terminal (\#1 or \#2) <br> Between motor block output terminals (\#1 to \#3) and secondary terminals other than motor block output terminals (\#1 to \#3) <br> 500 V AC for 1 min <br> Between DC power supply terminal (\#1 or \#2) and frame ground terminal (\#3) Between DC power supply terminal (\#1 or \#2) and secondary terminals other than motor block output terminals (\#1 to \#3) |
|  |  | Case material | Main unit: Modified PPE (case), polycarbonate (board holder, front mask) Display unit: Modified PPE (case), polycarbonate (back cover), PET film (protective sheet) |
|  |  | Case color | Black |
|  |  | Applicable standards | EN 61010-1, EN 61326-1 (for use in industrial locations) <br> Note: During EMC testing, the reading or output may fluctuate by the equivalent of $\pm 10 \%$ FS. <br> cULus: UL 61010-1, CSA C22.2 No. 61010-1 (applicable model needs to be selected) |
|  |  | Overvoltage category | Category II (IEC 60364-4-443, IEC 60664-1) |
|  |  | Installation | Main unit: Mounting on a DIN rail (standard) or on the display unit using the mounting bracket <br> Display unit: Mounting using $\varphi 3$ screws (standard) or the mounting bracket (mount in a $92 \times 92 \mathrm{~mm}$ hole) |
|  |  | Weight | Main unit: 500 g max. <br> Display unit: 150 g max. <br> Integrated mounting bracket: 150 g max. |
|  |  | Built-in clock accuracy | Monthly error: $\pm 140 \mathrm{~s}$ ( $\pm 65 \mathrm{~s}$ if the clock block with battery is used) <br> Note: The time is reset to 00:00:00 1/1/2000 (default) at power-on (including power restoration). <br> Note: For a firmware version of the MAIN block 3.*.* or earlier (* represents any number), the time is reset to 00:00:00 1/1/2014 (default). |


| General specifications | Standard conditions | Ambient temperature | $23{ }^{\circ} \mathrm{C}-2 /+5{ }^{\circ} \mathrm{C}$ |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | Ambient humidity | $60 \pm 5$ \% RH |  |
|  |  | Power voltage | AC models: 105 V AC $\pm 10$ \%. DC models: 24 V DC $\pm 5$ \% |  |
|  |  | Power frequency | AC models: $50 \mathrm{~Hz} \pm 1 \%, 60 \mathrm{~Hz} \pm 1 \%$ |  |
|  |  | Vibration | $0 \mathrm{~m} / \mathrm{s}^{2}$ |  |
|  |  | Shock | $0 \mathrm{~m} / \mathrm{s}^{2}$ |  |
|  |  | Mounting angle | Main unit: Reference plane $\pm 3^{\circ}$, Display unit: No restriction (if mounted separately from the main unit) |  |
|  |  | Space | Reference plane $\pm 10^{\circ}$ (main unit, and main unit and display unit in integrated mounting), no restriction for display unit in standard mounting |  |
|  | Operating conditions | Ambient temperature | 0 to $50^{\circ} \mathrm{C}$ ( 0 to $40^{\circ} \mathrm{C}$ if 2 or more main units are gang-mounted), 0 to $50^{\circ} \mathrm{C}$ (display unit) |  |
|  |  | Ambient humidity | 10 to $90 \% \mathrm{RH}$ (without condensation) |  |
|  |  | Rated power | AC models: 100 to 240 V AC (operating input voltage: 85 to 264 V AC) DC models: 24 V DC (operating input voltage: 20.4 to 28.8 V DC) |  |
|  |  | Power frequency | AC models: $50 \mathrm{~Hz} \pm 2$ \% or $60 \mathrm{~Hz} \pm 2 \%$ |  |
|  |  | Vibration | 0 to $5 \mathrm{~m} / \mathrm{s}^{2}$ (10 to 60 Hz for 2 h each in $\mathrm{x}, \mathrm{y}$, and z directions) |  |
|  |  | Shock | 0 to $100 \mathrm{~m} / \mathrm{s}^{2}$ |  |
|  |  | Mounting angle | Reference plane $\pm 10^{\circ}$ (main unit, and main unit and display unit in integrated mounting), no restriction for display unit in standard mounting |  |
|  |  | Altitude | 2000 m max. |  |
|  |  | Pollution degree | 2 |  |
|  |  | Installation location | Indoors |  |
|  |  | Space | 50 mm min. above and below <br> No space is needed around the display unit |  |
|  | Transportation and storage conditions | Ambient temperature | -20 to $+70^{\circ} \mathrm{C}$ |  |
|  |  | Ambient humidity | 10 to $95 \% \mathrm{RH}$ (without condensation) |  |
|  |  | Vibration | 0 to $10 \mathrm{~m} / \mathrm{s}^{2}$ (10 to 60 Hz for 2 h each in $\mathrm{x}, \mathrm{y}$, and z directions) |  |
|  |  | Shock | 0 to $300 \mathrm{~m} / \mathrm{s}^{2}$ (3 times each in $\mathrm{x}, \mathrm{y}$, and z directions) |  |
| Accessories |  | Item | Qty. | Application |
|  | Standard gasket |  | 1 | For the display unit of the standard model (C7G _ 4). |
|  | Display unit mounting screws (6 mm) |  | 5 | Standard model (C7G _ 4) |
|  | Display unit mounting screws (10 mm) |  | 5 | Standard model (C7G _ 4) |
|  | Set screws (for securing temporarily) |  | 2 | Standard model (C7G _ 4) |
|  | Gasket with $92 \times 92 \mathrm{~mm}$ hole |  | 1 | Integrated mounting model (C7G _ 3) |
|  | Integrated-mounting bracket |  | 1 | Integrated mounting model (C7G _ 3) |
|  | Display unit mounting screws (6 mm) |  | 5 | Integrated mounting model (C7G _ 3) |
|  | Integrated-mounting cable |  | 1 | Integrated mounting model (C7G _ 3) |

Table 1. Input types and ranges

| Input type | Range type Nos. | Sensor | Range |  | Accuracy | Resolution | Burnout |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Thermocouple | 1 | K | -200 to | $+1200{ }^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit *1 | $0.1{ }^{\circ} \mathrm{C}$ | Upscale |
|  | 2 | K | 0 to | $1200{ }^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ | (110 \% FS) |
|  | 3 | K | 0 to | $800^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 4 | K | 0 to | $600^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 5 | K | 0 to | $400{ }^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 6 | K | -200 to | $+400{ }^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit *1 | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 7 | K | -200 to | $+200^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit *1 | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 8 | J | 0 to | $1200{ }^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 9 | J | 0 to | $800^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 10 | J | 0 to | $600{ }^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 11 | J | -200 to | $+400{ }^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit *1 | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 12 | E | 0 to | $800^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 13 | E | 0 to | $600{ }^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 14 | T | -200 to | $+400{ }^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit *1 | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 15 | R | 0 to | $1600{ }^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit *2 | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 16 | S | 0 to | $1600{ }^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit *2 | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 17 | B | 0 to | $1800{ }^{\circ} \mathrm{C}$ | $\pm 0.2$ \% FS $\pm 1$ digit *3 | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 20 | WRe5-26 | 0 to | $1400{ }^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
|  | 21 | WRe5-26 | 0 to | $2300{ }^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |

*1. For -200 to $0^{\circ} \mathrm{C}, \pm 0.2 \% \mathrm{FS} \pm 1$ digit
${ }^{*}$ 2. For 0 to $100^{\circ} \mathrm{C}, \pm 0.2 \% \mathrm{FS} \pm 1$ digit
${ }^{*} 3$. For 0 to $260^{\circ} \mathrm{C}, \pm 4 \% \mathrm{FS} \pm 1$ digit. For 260 to $800^{\circ} \mathrm{C}, \pm 0.4 \% \mathrm{FS} \pm 1$ digit

| Input type | Range | Sensor | Range |  | Accuracy | Resolution | Burnout |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Resistance temperature detector (RTD) | 41 | Pt100 | -200 to | $+500{ }^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ | $\begin{gathered} \text { Upscale } \\ (110 \% \text { FS }) \end{gathered}$ |
|  | 43 | Pt100 | -200 to | $+200{ }^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 45 | Pt100 | -100 to | $+300{ }^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 47 | Pt100 | -100 to | $+200{ }^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 49 | Pt100 | -100 to | $+150{ }^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 51 | Pt100 | -50 to | $+200{ }^{\circ} \mathrm{C}$ | $\pm 0.1 \% \mathrm{FS} \pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 53 | Pt100 | -50 to | $+100^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 55 | Pt100 | -60 to | $+40^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 57 | Pt100 | -40 to | $+60^{\circ} \mathrm{C}$ | $\pm 0.1 \% \mathrm{FS} \pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 59 | Pt100 | -10 to | $+60^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 61 | Pt100 | 0 to | $100^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 63 | Pt100 | 0 to | $200^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 65 | Pt100 | 0 to | $300^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.01{ }^{\circ} \mathrm{C}$ |  |
|  | 67 | Pt100 | 0 to | $500^{\circ} \mathrm{C}$ | $\pm 0.1$ \% FS $\pm 1$ digit | $0.1{ }^{\circ} \mathrm{C}$ |  |
| Linear | 86 | Voltage (V) | 1 to | 5 V | $\pm 0.1$ \% FS $\pm 1$ digit | 1/90000 or better | Downscale (-10 \% FS) |
|  | 87 | Voltage (V) | 0 to | 5 V | $\pm 0.1$ \% FS $\pm 1$ digit |  | Burnout not detected (around 0 \% FS) |
|  | 88 | Voltage (V) | 0 to | 10 V | $\pm 0.1$ \% FS $\pm 1$ digit |  | Burnout not detected (around 0 \% FS) |
|  | 89 | Current (mA) | 0 to | 20 mA | $\pm 0.1$ \% FS $\pm 1$ digit |  | Burnout not detected (around 0 \% FS) |
|  | 90 | $\begin{aligned} & \text { Current } \\ & (\mathrm{mA}) \end{aligned}$ | 4 to | 20 mA | $\pm 0.1$ \% FS $\pm 1$ digit |  | Downscale (-10 \% FS) |


| Input type | Range type <br> Nos. | Sensor | Range | Accuracy | Resolution | Burnout |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Not used | 0 | None | Always 0 | --- | --- | - |

## Input sensor standards reference

$\begin{array}{lll}\text { Thermocouple } & \text { K, E, J, T, B, R, S: } & \text { JIS C 1602-2015 } \\ & \text { WRe5-26: } & \text { ASTM E988-96 (Reapproved 2002) } \\ & & \text { (JIS C 1602:2015, C thermocouple) }\end{array}$
Resistance temperature detector Pt100: JIS C 1604-2013

Table 2. Compact data storage (CDS) and health index settings

| Item |  | Specifications | Note |
| :---: | :---: | :---: | :---: |
| Compact data storage (CDS) | Recording cycle | 0: Same as sampling cycle <br> 1: 0.1 s <br> 2: 1 s <br> 3: 10 s <br> 4: 1 min <br> 5: 10 min | Set according to the response time of the control target |
|  | Operation type | 0: Stop <br> 1: DI1 status <br> 2: DI2 status <br> 11 to 26: Events 1 to 16 <br> 1024 to 2047: Standard bit codes | Operates when ON and records data. |
| Health Index | Operation type | 0: Stop <br> 1: DI1 status <br> 2: DI2 status <br> 11 to 26: Events 1 to 16 <br> 1024 to 2047: Standard bit codes | Operates for loops 1 to 4 individually |
|  | $R$ value scale | 0 to 10 | Result of primary operation $\times$ power of 10 |
|  | Ideal data | 0.0000 to 32000 |  |
|  | Deviation low limit | 0.0000 to 32000 | No low limit when 0.0000 |
|  | Deviation high limit | 0.0000 to 32000 | No high limit when 0.0000 |
|  | SP high limit | -32000 to +32000 |  |
| File | Saved to | MicroSD memory card |  |
|  | Saving timing | Every 8 KB |  |
|  | Saved format | Text (CSV) | Extension: .DAT |
|  | Number of files saved | 65000 max. |  |
| Records <br> (for Data selection = Stan- <br> dard) | Context section | P (Proportional band) | Setting at CDS start |
|  |  | I (Integral time) |  |
|  |  | D (Derivative time) |  |
|  |  | OL |  |
|  |  | OH |  |
|  |  | SP limit |  |
|  |  | Definite R value | Definite value at CDS end |
|  | Chronological data selection (cyclic recording) | Timestamp |  |
|  |  | SP |  |
|  |  | PV |  |
|  |  | MV |  |
|  |  | $R$ value |  |
|  |  | RMS current value | CT input* |
|  |  | RMS voltage value | VT input* |
|  |  | Actuator (heater) resistance | Calculates using the CT input current and the VT input voltage) |
| Records (for Data selection = Custom) | Number of data items | 1 to 40 |  |
|  | Data type (Data 1 to 40) | 1024 to 2047: Standard bit codes 2048 to 3071: Standard numerical codes <br> Table 3, "Standard bit codes" (p. 10), <br> Table 4, "Standard numerical codes" (p. 11). | The number of items set in "Number of data items" is enabled. |
|  | Recording | Data is recorded periodically according to the settings for "Data type" and "Number of data items." |  |
| Diagnostic parameter | Health index | Definite R value | In the normalization responsiveness (Kp/Tp) transfer function, gain is defined as Kp and the time constant as Tp. |
|  | Calculation timing | When the health index function is running | Calculated from the data when the PV is rising during batch processing. |

[^0]V-P block: CT1 RMS current, CT2 RMS current

Table 3. Standard bit codes
The range of standard bit codes is 1024 to 2027.
Codes not listed below are reserved for the system, so do not use them for configuration.

| Standard bit code | Meaning of the standard bit codes | Standard bit code | Meaning of the standard bit codes |
| :---: | :---: | :---: | :---: |
| 1024 | Always 0 (Off) | 1169 | DI/DO2 terminal status |
| 1025 | Always 1 (On) | 1170 | DI/DO3 terminal status |
| 1088 | Event 1 | 1171 | DI/DO4 terminal status |
| 1089 | Event 2 | 1172 | DI/DO5 terminal status |
| 1090 | Event 3 | 1173 | DI/D06 terminal status |
| 1091 | Event 4 | 1174 | DI/DO7 terminal status |
| 1092 | Event 5 | 1280 | V-P terminal status (block A2) |
| 1093 | Event 6 | 1281 | V-P terminal status (block B2) |
| 1094 | Event 7 | 1282 | V-P terminal status (block A1) |
| 1095 | Event 8 | 1283 | V-P terminal status (block B1) |
| 1096 | Event 9 | 1408 | User-defined bit 1 |
| 1097 | Event 10 | 1409 | User-defined bit 2 |
| 1098 | Event 11 | 1410 | User-defined bit 3 |
| 1099 | Event 12 | 1411 | User-defined bit 4 |
| 1100 | Event 13 | 1412 | User-defined bit 5 |
| 1101 | Event 14 | 1413 | User-defined bit 6 |
| 1102 | Event 15 | 1414 | User-defined bit 7 |
| 1103 | Event 16 | 1415 | User-defined bit 8 |
| 1120 | CT1 heater burnout detection | 1416 | User-defined bit 9 |
|  | (block A2) | 1417 | User-defined bit 10 |
| 1121 | CT2 heater burnout detection | 1418 | User-defined bit 11 |
|  | (block A2) | 1419 | User-defined bit 12 |
| 1122 | CT1 heater burnout detection | 1420 | User-defined bit 13 |
|  | (block B2) | 1421 | User-defined bit 14 |
| 1123 | CT2 heater burnout detection | 1422 | User-defined bit 15 |
|  | (block B2) | 1423 | User-defined bit 16 |
| 1124 | CT1 heater burnout detection | 1440 | Result of logical operation 1 |
|  | (block A1) | 1441 | Result of logical operation 2 |
| 1125 | CT2 heater burnout detection | 1442 | Result of logical operation 3 |
|  | (block A1) | 1443 | Result of logical operation 4 |
| 1126 | CT1 heater burnout detection (block B1) | 1444 | Result of logical operation 5 |
|  |  | 1445 | Result of logical operation 6 |
| 1127 | CT2 heater burnout detection (block B1) | 1446 | Result of logical operation 7 |
| 1128 |  | 1447 | Result of logical operation 8 |
|  | CT1 overcurrent detection (block <br> A2) | 1448 | Result of logical operation 9 |
| 1129 |  | 1449 | Result of logical operation 10 |
|  | A2) | 1450 | Result of logical operation 11 |
| 1130 | CT1 overcurrent detection (block | 1451 | Result of logical operation 12 |
|  |  | 1452 | Result of logical operation 13 |
| 1131 |  | 1453 | Result of logical operation 14 |
|  |  | 1454 | Result of logical operation 15 |
| 1132 | CT1 overcurrent detection (block | 1455 | Result of logical operation 16 |
|  |  | 1504 | At CDS start |
| 1133 | CT2 overcurrent detection (block | 1505 | Loop 1 health index running |
|  |  | 1506 | Loop 2 health index running |
| 1134 | CT1 overcurrent detection (block | 1507 | Loop 3 health index running |
|  |  | 1508 | Loop 4 health index running |
| 1135 | CT2 overcurrent detection (block | 1517 | Display unit connection status |
| 1136 |  | 1518 | Additional display unit connection status |
|  | A2) | 1568 | Loop 1 RUN/READY status |
| 1137 | CT2 short-circuit detection (block | 1569 | Loop 2 RUN/READY status |
|  | A2) | 1570 | Loop 3 RUN/READY status |
| 1138 | CT1 short-circuit detection (block | 1571 | Loop 4 RUN/READY status |
|  |  | 1584 | Loop 1 Auto/manual status |
| 1139 |  | 1585 | Loop 2 Auto/manual status |
|  |  | 1586 | Loop 3 Auto/Manual status |
| 1140 | CT1 short-circuit detection (block | 1587 | Loop 4 Auto/Manual status |
|  |  | 1600 | Loop 1 AT stop/start status |
| 1141 |  | 1601 | Loop 2 AT stop/start status |
|  |  | 1602 | Loop 3 AT stop/start status |
| 1142 | CT1 short-circuit detection (block | 1603 | Loop 4 AT stop/start status |
|  |  | 1616 | Loop 1 LSP/RSP status |
| 1143 | CT2 short-circuit detection (blockB1) | 1617 | Loop 2 LSP/RSP status |
|  |  | 1648 | Loop 1 SP ramp-up in progress |
| 1168 | DI/DO1 terminal status | 1649 | Loop 2 SP ramp-up in progress |


| Standard <br> bit code | Meaning of the standard bit codes |
| :---: | :--- |
| 1650 | Loop 3 SP ramp-up in progress |
| 1651 | Loop 4 SP ramp-up in progress |
| 1652 | Loop 1 SP ramp-down in progress |
| 1653 | Loop 2 SP ramp-down in progress |
| 1654 | Loop 3 SP ramp-down in progress |
| 1655 | Loop 4 SP ramp-down in progress |
| 1792 | All typical alarms (logical OR of <br> all alarms be displayed) |
| 1824 | Loop 1 PV low limit error |
| 1825 | Loop 1 PV high limit error |
| 1826 | Loop 1 RSP low limit error |
| 1827 | Loop 1 RSP high limit error |
| 1828 | Loop 2 PV low limit error |
| 1829 | Loop 2 PV high limit error |
| 1830 | Loop 2 RSP low limit error |
| 1831 | Loop 2 RSP high limit error |
| 1832 | Loop 3 PV low limit error |
| 1833 | Loop 3 PV high limit error |
| 1836 | Loop 4 PV low limit error |
| 1837 | Loop 4 PV high limit error |
| 1880 | MFB input error |
| 1884 | Adjusting MFB |
| 1888 | Estimating MFB |
| 1896 | MFB adjustment error |
| 1900 | Motor drive output OPEN |
| 1904 | Motor rdive output CLOSE |
| 1920 | Reception monitoring 1 |
| 1921 | Reception monitoring 2 |
| 1922 | Reception monitoring 3 |
| 1952 | CT/VT input error (block A2 CT) |
| 1953 | CT/VT input error (block A2 VT) |
| 1954 | CT/VT input error (block B2 CT) |
| 1955 | CT/VT input error (block B2 VT) |
| 1956 | CT/VT input error (block A1 CT) |
| 1957 | CT/VT input error (block A1 VT) |
| 1958 | CT/VT input error (block B1 CT) |
| 1959 | CT/VT input error (block B1 VT) |
| 1960 | CT/CT input error (block A2 CT1) |
| 1961 | CT/CT input error (block A2 CT2) |
| 1962 | CT/CT input error (block B2 CT1) |
| 1963 | CT/CT input error (block B2 CT2) |
| 1964 | CT/CT input error (block A1 CT1) |
| 2008 | Block alarm SUB1 block failure |
| (DI DO) |  |
| 1965 | Block alarm MAIN block failure |
| 1966 | CT/CT input error (block A1 CT2) |
| 1967 | CT/CT input error (block B1 CT1) |
| 1973 | Memory error (block B1 CT2) |
| 1977 | Battery error (CLOCK block) |
| 1991 | Block error |
| 1992 | SD card error |
| 2000 | Block alarm IO failure (block A1) |
| 2001 | Block alarm IO failure (block A2) |
| 2002 | Block alarm IO failure (block A3) |
| 2003 | Block alarm IO failure (block A4) |
| 2004 | Block alarm IO failure (block B1) |
| 2006 | Block alarm IO failure (block B2) |
| Block alarm IO failure (block B3) |  |
|  | Block alarm I failure (block B4) |

## Table 4. Standard numerical codes

The range of the standard numerical codes is 2048 to 2790 .
Codes not listed below are reserved for the system, so do not use them for configuration.

| Standard numerical codes | Meaning of the standard numerical codes | Standard numerical codes | Meaning of the standard numerical codes |
| :---: | :---: | :---: | :---: |
| 2048 | Always 0.0 | 2499 | CT2 measured current when |
| 2111 | User-defined value 1 |  | output ON (block B2) |
| 2112 | User-defined value 2 | 2500 | CT1 measured current when |
| 2113 | User-defined value 3 |  | output ON (block A1) |
| 2114 | User-defined value 4 | 2501 | CT2 measured current when |
| 2115 | User-defined value 5 |  | ON (block A1) |
| 2116 | User-defined value 6 | 2502 | CT1 measured current when output ON (block B1) |
| 2117 | User-defined value 7 |  |  |
| 2118 | User-defined value 8 | 2503 | CT2 measured current when output ON (block B1) |
| 2119 | User-defined value 9 | 2512 | CT1 measured current when |
| 2120 | User-defined value 10 |  | output OFF (block A2) |
| 2121 | User-defined value 11 | 2513 | CT2 measured current when |
| 2122 | User-defined value 12 |  | (A2) |
| 2123 | User-defined value 13 | 2514 | CT1 measured current when |
| 2124 | User-defined value 14 |  | output OFF (block B2) |
| 2125 | User-defined value 15 | 2515 | CT2 measured current when |
| 2126 | User-defined value 16 |  | output OFF (block B2) |
| 2304 | Al (block A4) | 2516 | CT1 measured current when |
| 2305 | Al (block B4) |  | output OFF (block A1) |
| 2306 | Al (block A3) | 2517 | CT2 measured current when |
| 2307 | Al (block B3) |  |  |
| 2312 | PV (block A4) | 2518 | CT1 measured current when |
| 2313 | PV (block B4) |  |  |
| 2314 | PV (block A3) | 2519 | CT2 measured current when output OFF (block B1) |
| 2315 | PV (block B3) | 2528 | Loop 1 deviation (PV - SP) |
| 2320 | Loop 1 PV | 2529 | Loop 2 deviation (PV - SP) |
| 2321 | Loop 2 PV | 2530 | Loop 3 deviation (PV - SP) |
| 2322 | Loop 3 PV | 2531 | Loop 4 deviation (PV - SP) |
| 2323 | Loop 4 PV | 2544 | CT input value (block A2) |
| 2336 | Loop 1 SP (in use) | 2545 | CT input value (block B2) |
| 2337 | Loop 2 SP (in use) | 2546 | CT input value (block A1) |
| 2338 | Loop 3 SP (in use) | 2547 | CT input value (block B1) |
| 2339 | Loop 4 SP (in use) | 2548 | VT input value (block A2) |
| 2352 | Loop 1 SP (final value) | 2549 | VT input value (block B2) |
| 2353 | Loop 2 SP (final value) | 2550 | VT input value (block A1) |
| 2354 | Loop 3 SP (final value) | 2551 | VT input value (block B1) |
| 2355 | Loop 4 SP (final value) | 2552 | Resistance (block A2) |
| 2416 | Loop 1 MV | 2553 | Resistance (block B2) |
| 2417 | Loop 2 MV | 2554 | Resistance (block A1) |
| 2418 | Loop 3 MV | 2555 | Resistance (block B1) |
| 2419 | Loop 4 MV | 2656 | Event 1 timer remaining time |
| 2432 | Loop 1 MV for heating | 2657 | Event 2 timer remaining time |
| 2433 | Loop 2 MV for heating | 2658 | Event 3 timer remaining time |
| 2434 | Loop 3 MV for heating | 2659 | Event 4 timer remaining time |
| 2435 | Loop 4 MV for heating | 2660 | Event 5 timer remaining time |
| 2448 | Loop 1 MV for cooling | 2661 | Event 6 timer remaining time |
| 2449 | Loop 2 MV for cooling | 2662 | Event 7 timer remaining time |
| 2450 | Loop 3 MV for cooling | 2663 | Event 8 timer remaining time |
| 2451 | Loop 4 MV for cooling | 2664 | Event 9 timer remaining time |
| 2464 | MFB opening amount (estimated) | 2665 | Event 10 timer remaining time |
| 2472 | MFB opening amount (actual | 2666 | Event 11 timer remaining time |
|  | value) | 2667 | Event 12 timer remaining time |
| 2479 | MFB count value | 2668 | Event 13 timer remaining time |
| 2496 | CT1 measured current when output ON (block A2) | 2669 | Event 14 timer remaining time |
| 2497 | CT2 measured current when | 2670 | Event 15 timer remaining time |
|  | output ON (block A2) | 2671 | Event 16 timer remaining time |
| 2498 | CT1 measured current when output ON (block B2) | 2736 | CT1 Time proportioning current (block A2) |
|  |  | 2737 | CT2 Time proportioning current (block A2) |


| Standard <br> numeri- <br> cal codes | Meaning of the standard <br> numerical codes |
| :---: | :--- |
| 2738 | CT1 Time proportioning current <br> (block B2) |
| 2739 | CT2 Time proportioning current <br> (block B2) |
| 2740 | CT1 Time proportioning current <br> (block A1) |
| 2741 | CT2 Time proportioning current <br> (block A1) |
| 2742 | CT1 Time proportioning current <br> (block B1) |
| 2743 | CT2 Time proportioning current <br> (block B1) |
| 2752 | Loop 1 definite R value |
| 2753 | Loop 2 definite R value |
| 2754 | Loop 3 definite R value |
| 2755 | Loop 4 definite R value |
| 2760 | Loop 1 R value |
| 2761 | Loop 2 R value |
| 2762 | Loop 3 R value |
| 2763 | Loop 4 R value |
| 2768 | AO-C percent output value (block <br> A2) |
| 2769 | AO-C percent output value (block <br> B2) |
| 2770 | AO-C percent output value (block <br> A1) |
| 2771 | AO-C percent output value (block <br> B1) |
| 2776 | V-P percent output value (block <br> A2) |
| 2777 | V-P percent output value (block <br> B2) |
| 2778 | V-P percent output value (block <br> A1) |
| 2779 | V-P percent output value (block <br> B1) |
| 2787 | TP percent output value (DO4) |
| 2788 | TP percent output value (DO5) |
| 2789 | TP percent output value (DO6) |
| 2790 | TP percent output value (DO7) |


*1. A rear-mounting bracket and a dedicated cable for connecting the display unit are included with the product.
*2. RSP1 can be switched for use as PV3.
*3. RSP2 can be switched for use as PV4.
*4. Current transformer (CT) and voltage transformer (VT) are not included.
*5. Additional display unit is not included.

| Symbol | Block Name | Description |
| :---: | :--- | :--- |
| AI | Analog Input | Full-multi range (thermocouple, RTD, DC current, DC voltage) input $\times 1$ |
| V-P | Voltage pulse <br> output | Voltage pulse output (12 V DC) $\times 1$ <br> Two input terminals for the current transformer (CT) for detecting heater <br> burnout, overcurrent, and short circuit are included. ${ }^{* 4}$ |
| AO-C | Analog current <br> output | Current output (4-20 mA DC $/ 0-20 \mathrm{~mA} \mathrm{DC}) \times 1$ <br> Input terminals for the current transformer (CT) for measuring current and <br> the voltage transformer (VT) for measuring voltage are included (1 each). |
| HMI2 | Additional display <br> unit | Connector for the second display unit *5 |
| Clock | Clock function | Clock (available for CDS and health index) with a battery |

- Model No. recommendations

| Current output |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Digits 8 \& 9 | If 1 output: C0 |  | $\Rightarrow$ | If 2 outputs: CC |  | $\Rightarrow$ | If 3 outputs: FC |  |  | $\Rightarrow$ | If 4 outputs: FF |  |  |
|  | (A) (B) |  |  | (A) (B) |  |  | (A) (B) |  |  | A B <br> AOC AO-C <br> AO-C AO-C |  |  |  |
|  |  | $\begin{aligned} & 1 \\ & <1 \\ & 2 \end{aligned}$ |  |  | -1 |  | AO-C | $\begin{gathered} 1 \\ 0 . c \\ <2 \end{gathered}$ |  |  |  |  |  |
|  | AO-C |  |  |  | AO-C 2 |  |  |  |  |  |  |  |  |
| Analog input |  |  |  |  |  |  |  |  |  |  |  |  |  |
| Digits 6 \& 7 | If 1 input: 10 |  | $\Rightarrow$ | If 2 inputs: 11 |  | $\Rightarrow$ | If 3 inputs: 21 |  |  | $\Rightarrow$ | If 4 inputs: $\mathbf{2 2}$ |  |  |
|  | (A) (B) |  | (A) (B) |  |  |  | (A) (B) |  |  |  | (A) B |  |  |
|  |  | (3) |  |  |  |  | AI |  | (3) |  | AI | AI | 3 |
|  | AI | 4 |  | AI | AI 4 |  | AI | AI | 4 |  | AI | AI | 4 |

- Sample block implementations for model No. and slot positions
Digits 6-9 \& slot positions

Example for C7GA411CCODOO
(A) (B)


Model selection (models with motor output)


Model selection (display unit)


## Accessories (sold separately)

| Name | Model No. |
| :--- | :---: |
| SLP-C7 Smart Loader Package (free version) * | SLP-C7FJ91 |
| SLP-C7 Smart Loader Package (paid version) | SLP-C7-J91 |
| Current transformer (5.8 mm in diameter) | QN206A |
| Current transformer (12 mm in diameter) | QN212A |
| Voltage transformer (for 200 V AC) | $\mathbf{8 1 4 0 6 7 2 5 - 0 0 3}$ |

## Model No. and loop type

The following table shows the possible combinations of model No. and loop type with regard to analog input.
OK : Combination is possible

- : Combination is not possible

For possible combinations, slots for AI blocks and loop PVs or RSPs assigned to the blocks are shown.

| PV1 | $:$ LOOP1 PV |
| :--- | :--- |
| PV2 | : LOOP2 PV |
| PV3 | $:$ LOOP3 PV |
| PV4 | : LOOP4 PV |
| RSP1 | : LOOP1 RSP |
| RSP2 | : LOOP2 RSP |

Not used : The AI block slot exists but is not assigned to the PV or RSP of a loop.

| Loop type | 6th and 7th digits of the model No. (C7GA |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 10 | 20 | 11 | 21 | 22 |
| 0: 1 loop | A4: PV1 | $\quad$ OK A4: PV1 A3: Not used | OK <br> A4: PV1 <br> B4: Not used | OK <br> A4: PV1 <br> A3: Not used <br> B4: Not used | OK <br> A4: PV1 <br> A3: Not used <br> B4: Not used <br> B3: Not used |
| $\text { 1: } 1 \text { loop + } 1 \text { RSP }$ | - | OK <br> A4: PV1 <br> A3: RSP1 | - | OK <br> A4: PV1 <br> A3: RSP1 <br> B4: Not used | OK <br> A4: PV1 <br> A3: RSP1 <br> B4: Not used <br> B3: Not used |
| 2: 2 loops | - | - | A4: PV1 B4: PV2 | OK <br> A4: PV1 <br> A3: Not used <br> B4: PV2 | OK <br> A4: PV1 <br> A3: Not used <br> B4: PV2 <br> B3: Not used |
| $\text { 3: } 2 \text { loops + } 1 \text { RSP }$ | - | - | - | OK <br> A4: PV1 <br> A3: RSP1 <br> B4: PV2 | OK <br> A4: PV1 <br> A3: RSP1 <br> B4: PV2 <br> B3: Not used |
| 4: 2 loops + 2 RSPs | - | - | - | - | A4: PV1 <br> A3: RSP1 <br> B4: PV2 <br> B3: RSP2 |
| 5: 3 loops | - | - | - | OK <br> A4: PV1 <br> A3: PV3 <br> B4: PV2 | OK <br> A4: PV1 <br> A3: PV3 <br> B4: PV2 <br> B3: Not used |
| $\text { 6: } 3 \text { loops + } 1 \text { RSP }$ | - | - | - | - | OK <br> A4: PV1 <br> A3: PV3 <br> B4: PV2 <br> B3: RSP2 |


| Loop type | 6th and 7th digits of the model No. (C7GA _-_- |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | 10 | 20 | 11 | 21 | 22 |
| 7: 4 loops | - | - | - | - | A4: PV1 <br> A3: PV3 <br> B4: PV2 <br> B3: PV4 |
| $\text { 8: } 1 \text { loop + } 1 \text { RSP }$ | - | - | OK <br> A4: PV1 <br> B4: RSP1 | - | - |
| 9: Internal cascade | - | - | OK <br> A4: PV1 (master) <br> B4: PV2 (slave) | OK <br> A4: PV1 (master) <br> A3: None <br> B4: PV2 (slave) | OK <br> A4: PV1 (master) <br> A3: None <br> B4: PV2 (slave) <br> B3: None |
| 10: Internal cascade +1 loop | - | - | - | OK <br> A4: PV1 (master) <br> A3: PV3 <br> B4: PV2 (slave) | OK <br> A4: PV1 (master) <br> A3: PV3 <br> B4: PV2 (slave) <br> B3: None |
| 11: Internal cascade +2 loops | - | - | - | - | OK <br> A4: PV1 (master) <br> A3: PV3 <br> B4: PV2 (slave) <br> B3: PV4 |

## ! Handling Precautions

- The value of unused AI blocks is not displayed. To display a PV value for monitoring even if there is no need to control it, select a loop type that has the AI block assigned to a PV. Ex.: if model No. digits 6-7 are "11," select a $2: 2$ loop, not a 0:1 loop. In such a case, since the PV is actually not controlled, it is not necessary to set the analog current output block or DI/DO block to output MV.


## External Dimensions and Mounting

- Standard mounting
(Unit: mm)

- Integrated mounting
(Unit: mm)



## Part Names and Functions

- Display unit

- Integrated mounting bracket (included with integrated mounting models)

- Main unit



## Terminal Connections



RS-485


Current output


Voltage pulse output


Motor drive output


## I/O isolation



*1. Blocks are functionally isolated from one another.
*2. The power block (AC) and the motor block (relay output) have reinforced insulation for isolation from all other circuits.

## Wiring Precautions

Before touching the main unit or display unit, or removing/ inserting cables, touch a grounded panel to discharge static electricity from your body.

## - Power input

AC power
1: AC power supply live line
2: AC power neutral line
3: Frame ground
DC power
DC power +
DC power -
3: Frame ground

## ! Handling Precautions

- Before touching the power input terminal box, shut off the input power.
- After completing the work, be sure to mount the cover on the power input terminal block.
Note: Applicable crimp terminal for power input: Crimp terminal for M4 ( 8.5 mm or less wide). Proper tightening torque: $1.4 \mathrm{~N} \cdot \mathrm{~m}$


## - DI/DO (digital inputs and outputs)

- : NC (not connected)

N1-7 : DI/DO 1-7 (DI and DO can be switched by changing the setting.)
V- : COM (common terminal)

- RS-485 (RS-485 communication port)

C1: ——DA (Data+)
C2: $\quad$ C3: Terminating resistor
C4: ——DB (Data-)
C5: - SG
$!$ Handling Precautions

- Connect a terminating resistor ( $120 \Omega, 1 / 2 \mathrm{~W}$ ) to both ends of the communication line.
- To connect two terminals (e.g., SG + another) together, use a crimp terminal for two wires.


## - Al block (analog input)

Current input Voltage input Thermocouple input RTD input


Allowable input voltage
Current input: -1.5 to +1.5 V
Voltage input: -15 to +15 V
Thermocouple input: -1.5 to +1.5 V

## - AO-C block (current outputs with CT and VT inputs)

1 : CT input
2 : CT/VT common
3 : VT input
4 : Current output +
5 : Current output -
Maximum allowable input
CT: 90 mA and 130 mA peak (AC) 1 V and 1.4 V peak (AC)
VT: 18 V and 26 V peak (AC)
Transient overvoltage
CT: supply voltage +250 V

## 1. Handling Precautions

- If a current transformer is used for a UL-compliant model, the transformer must be compliant with UL 2808 (categories XOBA and XOBA7). Do not use an uncertified current transformer.
- V-P block (voltage pulse outputs and 2 CT inputs)
1 : CT1
2 : Common
3 : CT2
4 : Voltage pulse output +
5 : Voltage pulse output -
Maximum allowable input
CT: 90 mA and 130 mA peak (AC)
1 V and 1.4 V peak (AC)
Transient overvoltage
CT: supply voltage +250 V
Load current:
Voltage pulse output: 25 mA max.
- MOTOR block (motor drive relay output: with MFB inputs)
\(\left.\begin{array}{ll}1 \& : OPEN <br>
2 \& : Common <br>
3 \& : CLOSE <br>
4 \& : MFB (Y) <br>
5 \& : MFB (T) <br>

6 \& : MFB (G)\end{array}\right]\)| Contact voltage: |
| :--- |
| 250 V AC / 125 V DC max. |
| $(100$ to $2500 \Omega)$ |

- Recommended ferrules

Manufacturer : Phoenix Contact
Crimp tool : CRIMPFOX 6
DI/DO, RS-485, AI, AO-C, V-P

| Designation | Order <br> Nos. | Cross section <br> $\left(\mathrm{mm}^{2}\right)$ | Note |
| :--- | :---: | :---: | :--- |
| AI 0,25-8 YE | 3203037 | 0.25 <br> (AWG24) | With insulation sleeve |
| AI 0,34-8-TQ | 3203066 | 0.34 <br> (AWG22) | With insulation sleeve |
| AI 0,5-8 WH | 3200014 | 0.50 <br> (AWG20) | With insulation sleeve |
| AI 0,75-8 GY | 3200519 | 0.75 <br> (AWG18) | With insulation sleeve |
| A1-8 | 3202517 | 1.00 <br> (AWG18) | Without insulation sleeve <br> Used to crimp two <br> JKPEV-S-2Px0.5SQ <br> together. |
| A1,5-7 | 3200263 | 1.50 <br> (AWG16) | Without insulation sleeve <br> Used to crimp two <br> JKPEV-S-2Px0.75SQ <br> together. |
| AI-TWIN 2X0, <br> 5-8 WH | 3200933 | 0.50 <br> (AWG20) | With insulation sleeve, <br> twin |
| AI-TWIN 2X0, <br> 75-8 GY | 3200807 | 0.75 <br> (AWG18) | With insulation sleeve, <br> twin |

## MOTOR

| Designation | Order <br> Nos. | Cross section <br> $\left(\mathrm{mm}^{2}\right)$ | Note |
| :--- | :---: | :---: | :---: |
| AI0,75-8 BU | 3200027 | 0.75 <br> (AWG18) | With insulation sleeve |
| AI1-8 RD | 3200030 | 1.00 <br> (AWG18) | With insulation sleeve |
| AI1,5-8 RD | 3201136 | 1.50 <br> (AWG16) | With insulation sleeve |
| AI2,5-10 BU | 3202533 | 2.00 <br> $(A W G 14)$ | With insulation sleeve |

## HMI (display unit)

| Designation | Order <br> Nos. | Cross section <br> $\left(\mathrm{mm}^{2}\right)$ | Note |
| :---: | :---: | :---: | :---: |
| AI0.25-6 YE | 3203024 | 0.25 <br> (AWG24) | For display connector, <br> without insulation sleeve |

## - USB connection

Connect the device to the PC using a USB-to-MicroUSB (type A or B) cable.

## ! Handling Precautions

- Connection and disconnection of the MicroUSB is hazardous because there is a power terminal nearby. Be sure to turn off the power before connecting or disconnecting the cable.
Note: Use a data communication cable.
- Inserting or removing a microSD memory card

Insert the microSD memory card all the way inside. Pushing on the memory card lightly will release it, enabling you to remove the card.

## ! Handling Precautions

- Do not insert or remove a memory card while the indicator near the connector is flashing.
- Connection and disconnection of a microSD memory card is hazardous because there is a power terminal nearby. Be sure to turn off the power before connecting or disconnecting the card.


## - Connecting the LAN cable for Ethernet

Use a Cat5E or higher LAN cable to make the connection.

## - Connecting the main unit to the display unit using a cable

- For standard mounting

Use a Cat5E or higher straight LAN cable to make the connection. (Cat5E, T568A, or T568B wiring. Both ends use RJ45 plug (8P8C modular).)
*1. A 4-core LAN cable cannot be used.
*2. If the length of the cable between the main unit and the display unit is from 30 m to 100 m , an external power source must be connected for the display unit.

- Wiring for integrated mounting

Insert the rod-shape crimp terminal lug of the wires with the specified colors of the included cable into the terminal block of the display unit..
1: White/orange
4: White/green
2: Blue
5: Green
3: White/blue
6: Brown

## Operation Check

After connecting the main unit to the display unit and turning on the power, a display will appear.
The display that first appears on the screen after power-on is called the initial display.
Display change button : Switches the display.
HOME button : Returns to the initial display.
MENU/Key lock button:
Displays the menu. Pressing the button for four seconds or longer locks the keys. Disabling the key lock is then the only operation permitted. Pressing the button again for four seconds or longer disables the key lock.

## Troubleshooting

## - Model number and serial number

The model number and serial number are printed on the top of the main unit near the front of the unit.
Have these numbers ready before contacting us.

## ■ Problems in installation

First, check the following regarding wiring:

- Connectors are securely inserted into the ports.
- Connectors are inserted into the right ports.
- Wires are properly connected to the power supply terminal block.
- Power is not turned on

| Status | Countermeasures |
| :--- | :--- |
| The status indicator on the <br> main unit is off. | Check the the power input connections <br> and voltage. |
| The status indicator on <br> the main unit is lit green or <br> the power indicator on the <br> display unit is off. | Standard mounting: <br> Check the LAN cable (8-core straight). <br> Check the connectors. <br> Integrated mounting: <br> Check if the wiring on the back of the <br> display unit is correct. Check connec- <br> tors on the main unit. |
| The power indicator on the <br> display unit is lit green and <br> the LCD remains black. | There may be a problem with the device. <br> Please contact us. |
| The status indicator on the <br> main unit is lit red. | There may be a problem with the device. <br> Please contact us. |

## - Blurry display

A thin film is applied on the protection sheet of the display for protection during transportation. Please remove the protective film.

- Alarms (the status indicator is blinking red) Please refer to the user's manual.
- microSD is trademark or registered trademark of SD-3C, LLC in the United States, other countries or both
- Modbus is a trademark and the property of Schneider Electric SE, its subsidiaries and affiliated companies.

Please read "Terms and Conditions" from the following URL before ordering and use
http://www.azbil.com/products/factory/order.html

## Azbil Corporation

## Advanced Automation Company

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Kanagawa 251-8522 Japan
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[^0]:    * The recorded details vary depending on the type of output block to which the MV is assigned.

    AO-C block: RMS current, RMS voltage, actuator resistance

